

Vivekanand College, Kolhapur (Autonomous)
Department of Electronics
Notice

Date: 21.11.2022

All the students of B.Sc. III Electronics are hereby informed that their internal examination for Semester V will be conducted in offline mode as per attached schedule.

Paper	Section	Section title	Marks	Date	Time
DSE 1005E1	I	Linear Integrated Circuits	10	28-11-2022	02:00pm-02.30pm
DSE 1005E1	II	8051 Microcontroller Interfacing and Embedded C	10	29-11-2022	02:00pm-02.30pm
DSE 1005E2	I	Instrumentation	10	30-11-2022	02:00pm-02.30pm
DSE 1005E2	II	Antenna and Wave Propagation	10	01-11-2022	02:00pm-02.30pm




(Dr. C. B. Patil)

Head
Department of Electronics
Vivekanand College, Kolhapur.

Q.1. Select the correct alternative

(2 M)

1. The output of a Schmitt trigger is a.....
 - a) pulse waveform.
 - b) triangular waveform
 - c) saw tooth waveform
 - d) Sine waveform
2. Virtual ground of an op-amp means.....
 - a) Input is grounded directly
 - b) Input is not physically grounded but terminal voltage is zero due to the other terminal is connected to the ground due to op-amp properties.
 - c) Both (a) and (b)
 - d) None of the above

Q.2. Solve any Two

(4*2=8M)

1. Draw the circuit diagram of an Op-Amp adder that can add three input signals. Derive an expression for output voltage.
2. Explain with circuit diagram V to I converter using Op-Amp.
3. Draw the circuit diagram of an Op-Amp as Subtractor that can add three input signals. Derive an expression for output voltage.
4. Explain Op-Amp as non-inverting amplifier with circuit diagram. Derive the expression for output voltage



Shri Swami Vivekanand ShikshanSanstha's
Vivekanand College, Kolhapur (Autonomous)
Class: B.Sc.-III, Semester-V, Internal Examination (2022-23)

Paper code: DSE-1005E1

Section II: 8051 Microcontroller Interfacing and Embedded C

Date:-29/11/2022

Time: 02:00pm to 02:30pm

Marks: 10

Q. 1 Select correct alternative for the following:

[2 x 1 = 2]

- i. Data range for signed char data type is -----
A) 0 to 255 B) -128 to +127 C) 0 to 65535 D) -32768 to +32767
- i. The output of Thumbwheel switch is in form.
A) Octal B) BCD C) Hex D) ASCII

Q.Solve any TWO:

[2 x 4 = 8]

- i. Mention the advantages of embedded-C over Assembly language. Tabulate various Data types in 8051-C
- ii. Write an 8051-C to generate a square wave on port P1 using timer delay.
- iii. Interface single seven segment display with 8051 and write 8051-C program to display the digits 0 to 9 continuously.
- iv. Draw an interfacing diagram of LED with 8051 and write 8051-C program to blink Led with certain time interval.



VIVEKANAND COLLEGE KOLHAPUR

B.Sc. III

Internal Examination 2022

Instrumentation

Marks: 10

Q.1) Select Correct alternatives

(02)

1) _____ transducers require external power source for their operation.

- a) Passive b) Active c) Both a & b d) None of these

2) Which of the following transducer is used for displacement measurement?

- a) Thermocouple b) LDR c) LVDT d) RTD

Q.2) Attempt any two

(08)

1) Write a note on thermistor.

2) Explain construction and working of LVDT

3) Explain with block diagram single channel DAS.

4) Explain concept of amplification and attenuation in signal conditioning.

5) Write a note on LDR.



VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

B.Sc. Part- III (Electronics) (Sem-V)

Internal Examination 2022

Course Code: DSE - 1005 E2

Section - II: Antenna and Wave Propagation

Q.1) Select most correct alternatives for the following (one mark each) [2 Marks]

- i. ----- propagation involves a radio signal that travels along the surface of the earth.
- | | |
|----------------|-------------------|
| A) Space wave | B) Sky wave |
| C) Ground wave | D) None of these. |
- ii. The widely used shape for patch antennas is -----
- | | |
|----------------|--------------|
| A) Rectangular | B) Circular |
| C) Elliptical | D) Parabolic |

Q.2) Attempt any Two (Four marks each) [8 Marks]

1. Explain the structure of microstrip patch antenna. Discuss its feed mechanism.
2. Explain the working principle and radiation pattern of monopole antenna.
3. Write the frequency range, wave propagation principle and two application of space wave propagation.
4. Define the following terms
 - a. Critical frequency
 - b. Maximum usable frequency
 - c. Skip distance
 - d. Virtual height.



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SUPPLIMENT

Suppliment No. :

Roll No. : 8358

Class : BSC-TY sem V

Signature of Supervisor

Subject : Electronics (LIC)

Test / Tutorial No. : Internal Exam

Div. :

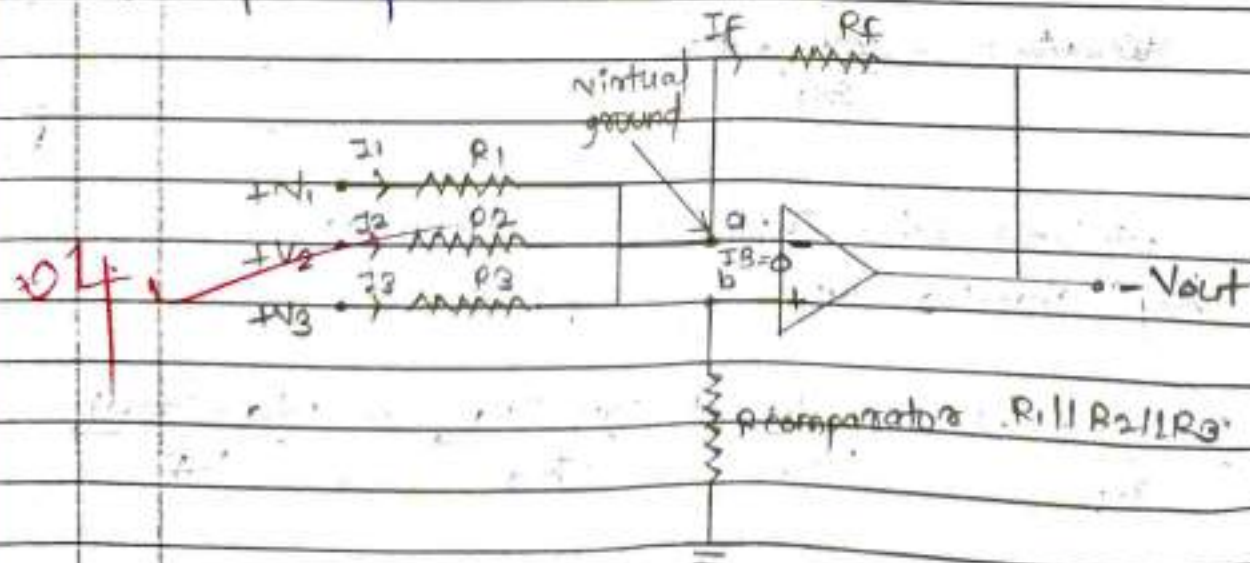
Q. 1)

1) d) sine waveform

2) b) Input is not physically grounded but terminal voltage is zero due to other terminal is connected to the ground due to op. amp properties.

Q. 2)

1) Op. amp as Adder



For ideal op. amp,

open loop gain is given as,

$$A_{OL} = \frac{V_o}{V_d} = \infty \quad \frac{V_o}{V_a - V_b} = 0$$

since, V_d is differential input voltage is finite.

$$\text{thus } V_a = V_b = 0 \quad \dots \quad V_2 - V_1 = 0$$

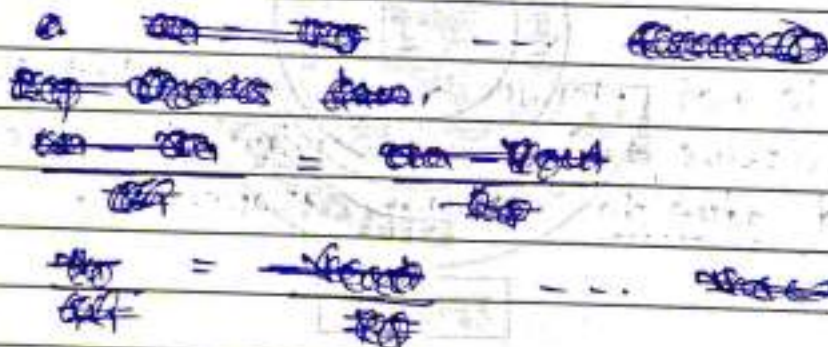
Since input impedance of op. amp $R_i = \infty$

that implies no current flows into or out of op. amp inverting terminal.

$$\therefore I_B = 0 \quad \text{--- (1)}$$

According to KCL at node 'a'

$$I_B = I_B + I_f \quad \text{--- (2)}$$



$$\therefore \frac{V_1 - V_a}{R_1} = - \frac{V_{out}}{R_f}$$

$$\therefore I_1 + I_2 + I_3 = I_f \quad \text{--- from (1)}$$

By ohm's law

$$\therefore \frac{V_1 - V_a}{R_1} + \frac{V_2 - V_a}{R_2} + \frac{V_3 - V_a}{R_3} = \frac{V_a - V_{out}}{R_f}$$

$$\therefore \frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} = - \frac{V_{out}}{R_f} \quad \text{--- } V_a = 0$$

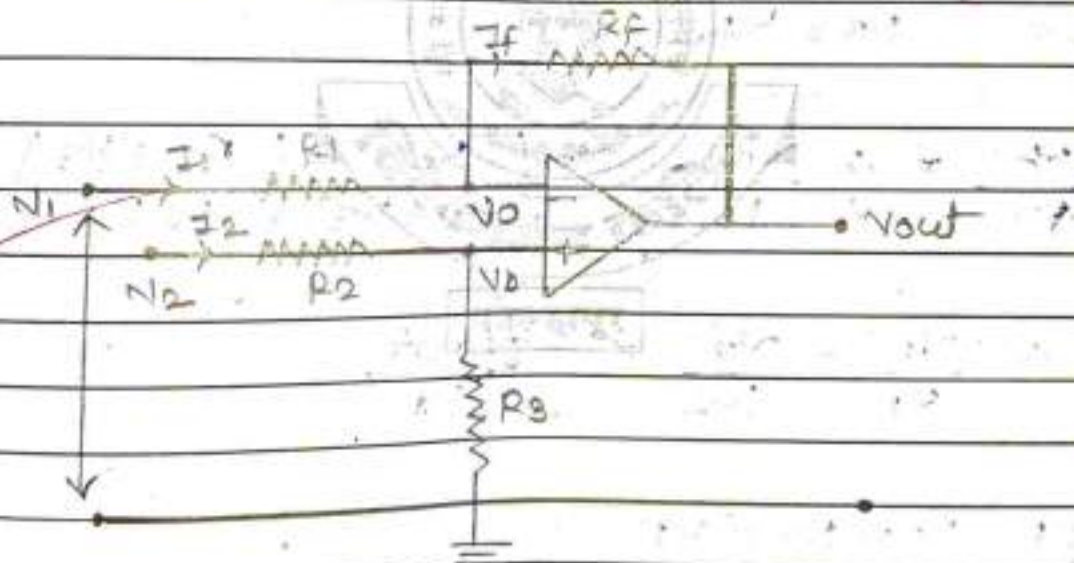
$$\text{If } R_1 = R_2 = R_3 = R_f$$

$$\therefore V_1 + V_2 + V_3 = -V_{out}$$

$$\therefore \boxed{V_{out} = -(V_1 + V_2 + V_3)}$$

That is output voltage is the negative sum of all input voltages.

g) op-amp as Subtractor



According to Kirchoff's Current law at \$V_2\$

$$I_{in} = I_f$$

$$\frac{V_1 - V_2}{R_1} = \frac{V_2 - V_{out}}{R_f}$$

$$\frac{V_1}{R_1} - \frac{V_2}{R_1} = \frac{V_2}{R_f} - \frac{V_{out}}{R_f}$$

$$\therefore \frac{V_1}{R_1} - \frac{V_a}{R_1} - \frac{V_a}{R_f} = -\frac{V_{out}}{R_f}$$

$$\therefore \frac{V_1}{R_1} - V_a \left(\frac{1}{R_1} + \frac{1}{R_f} \right) = -\frac{V_{out}}{R_f}$$

Now, by potential divider formula

$$\therefore V_a = V_b = V_2 \left(\frac{R_3}{R_2 + R_3} \right)$$

$$\therefore \frac{V_1}{R_1} - V_2 \left(\frac{R_3}{R_2 + R_3} \right) \left(\frac{R_1 + R_f}{R_1 R_f} \right) = -\frac{V_{out}}{R_f}$$

If $R_1 = R_2$ and
 $R_3 = R_f$

$$\therefore \frac{V_1}{R_1} - V_2 \left(\frac{R_3}{R_2 + R_3} \right) \left(\frac{R_2 + R_3}{R_2 R_3} \right) = -\frac{V_{out}}{R_f}$$

$$\therefore \frac{V_1}{R_1} - \frac{V_2}{R_2} = -\frac{V_{out}}{R_f}$$

If $R_1 = R_2 = R_f$

$$\therefore V_1 - V_2 = -V_{out}$$

$$\boxed{V_{out} = V_2 - V_1}$$

Name - Prajakta Sunil Bidre

08/10

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08224

Shri Swami Vivekanand Shikshan Sanstha Kolhapur's

VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Signature
of
Supervisor

Suppliment No. :

Roll No. : 8359

Class : BSc.-III

Subject : Electronics [L1C]

Test / Tutorial No. : Electronics

Div. :

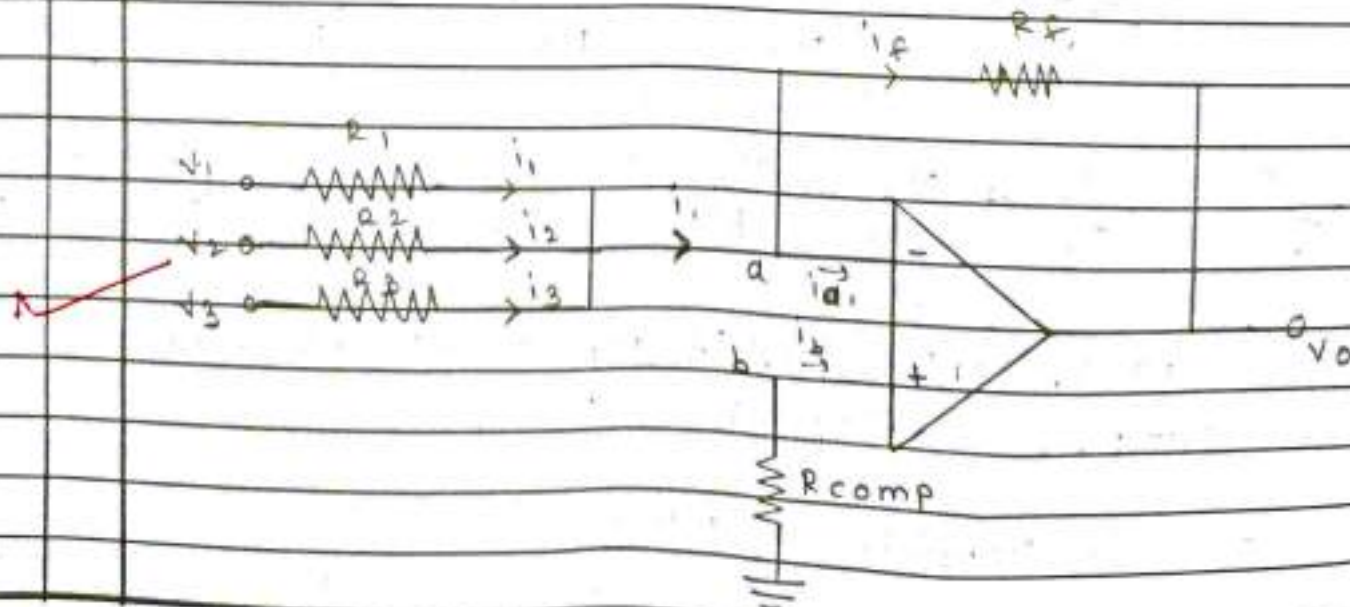
Q.1.

1) The output of schmitt trigger is a pulse and triangular waveform.

2) Virtual ground of an op-amp means Input is not physically grounded but terminal voltage is zero due to other terminal is connected to the ground due to op-amp properties.

Q.2

1) Op-amp adder that can add three inputs -



The circuit used as summing amplifier.
Assuming stable non-inverting linear operation, for ideal op-amp open loop gain.

$$A_{OL} = \frac{V_o}{V_d} = \frac{V_o}{V_b - V_a} = \infty$$

$$\therefore V_d = V_b - V_a = 0$$

input impedance R_i of the op-amp is ideally infinite, then op-amp inverting terminals

$$\text{i.e. } I_p = 0$$

The Kirchoff's current law equation at node 'a' can be,

$$i = I_p + I_f$$

$$\therefore i_1 + i_2 + i_3 = i_f$$

$$\therefore \frac{V_1 - V_a}{R_1} + \frac{V_2 - V_a}{R_2} + \frac{V_3 - V_a}{R_3} = -\frac{V_o}{R_f}$$

$$\therefore \frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} = -\frac{V_o}{R_f} \quad \text{--- [} \therefore V_a = 0 \text{]}$$

If in this circuit $R_1 = R_2 = R_3 = R_f = R$ the output voltage become,

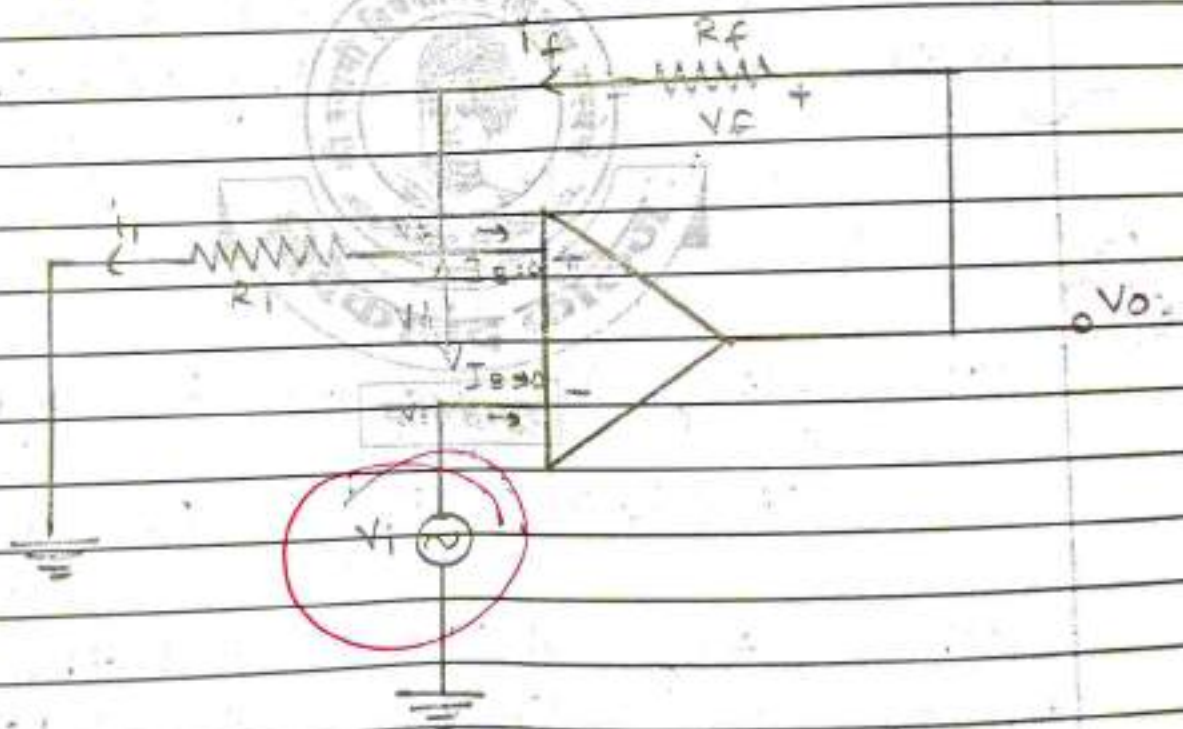
$$V_{os} = -(V_1 + V_2 + V_3)$$

$$V_o = -(V_1 + V_2 + V_3)$$

i.e. The output voltage is equal to the negative sum of all input voltages at the inverting terminal.

& The non-inverting the sum of positive sum of all input voltages is equal to the output voltage.

4) Op-amp as non-inverting amplifier-



The input voltage V_i is the applied to the directly to the non-inverting terminal. Apply stable linear operation for an ideal op-amp open loop gain.

$$A_{OL} = \frac{V_o}{V_d} = \frac{V_o}{V_1 - V_2} = \infty$$

Since V_0 is the finite differential input voltage,

$V_d = V_1 - V_2$ is forced to be zero, & thus,

$$V_i = V_1 = V_2$$

This voltage appears across the resistor R_f , so the current ~~so~~ the ideally, i_f is readily determined as the,

$$i_f = \frac{V_f}{R_f}$$

Since no current flows into or out of the op-amp inverting terminal,

i.e. $I_B = 0$

$\therefore i_i = i_f$

The voltage V_f appears R_f and is

$$V_i = i_f R_f = R_f i_f = R_f \frac{V_f}{R_i}$$

The voltage V_i , V_d , V_f and the output voltage V_0 constitute a closed loop.

Applying KVL to ~~across~~ the closed loop, we have,

$$V_0 = V_i + V_d + V_f$$

$$\therefore A_{OL} = \frac{V_0}{V_d} \approx \infty \therefore V_d = 0$$

$$\therefore V_0 = V_i + V_f$$

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of
Supervisor

Subject : Electronics

Test / Tutorial No. : Electronics

Div. :

$$\therefore V_o = V_i + \frac{R_i}{R_f} V_i$$

$$V_o = \left[1 + \frac{R_i}{R_f} \right] V_i$$

The closed loop voltage gain A_{CL} is given

$$A_{CL} = \frac{V_o}{V_i} = 1 + \frac{R_i}{R_f}$$

$$A_{CL} = 1 + \frac{R_i}{R_f}$$

Siddhesh Vishnu Jadhav

08/10

॥ ज्ञान, विज्ञान आणि सुसंस्कार यांसाठी शिक्षण प्रसार ॥

- शिक्षणमहर्षी डॉ. बापूजी साबुळे

08225

Shri Swami Vivekanand Shikshan Sanstha Kolhapur's

VIVEKANAND COLLEGE, KOLIAPUR (AUTONOMOUS)

SUPLIMENT

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Suppliment No. :

Roll No. : 8360

Class : BSC-III

Subject : Electronic (L2C)

Test / Tutorial No. :

Div. :

Q 11

→ 1) The output of a

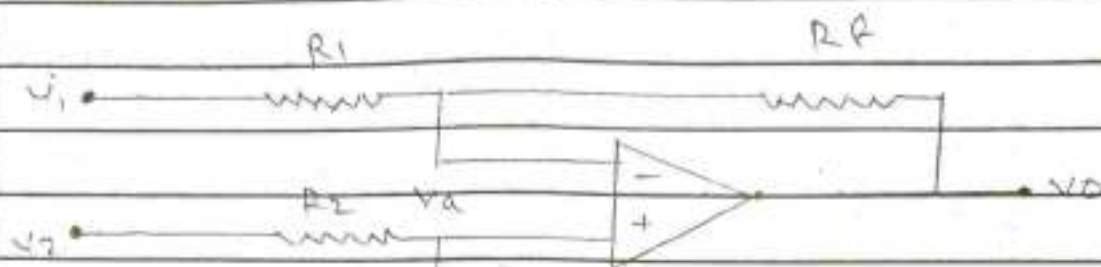
→ 1) pulse ~~waveform~~ sine waveform.

→ 2) Input is grounded directly.

कोल्हापूर

Q 2

→ 3) Block dig of op-Amp subtractors.



Dig shows op-Amp subtractor.

V_2 is grounded.

$$\therefore V_2 = 0$$

then the circuit is ^{inverting} inverting op-Amp

then the output of the ^{inverting} inverting op-Amp

$$V_{O2} = \frac{R_f}{R_i} \cdot V_1 \quad \text{--- (i)}$$

V_1 is grounded.

$$V_1 = 0$$

then the circuit is noninverting op-Amp

$$\therefore V_{O1} = \left[1 + \frac{R_f}{R_1} \right] \left[\frac{R_3}{R_2 + R_3} \right] V_2 \quad \text{--- (ii)}$$

from eq (i) and (ii)

Use using the superposition principle

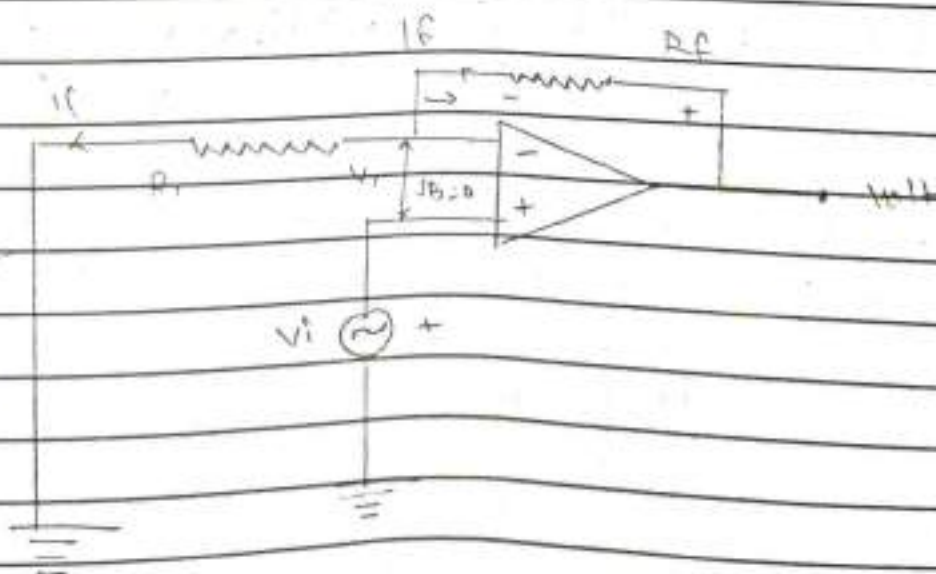
$$V_O = V_{O1} + V_{O2}$$

$$= \left[-\frac{R_f}{R_1} \right] V_1 + \left[1 + \frac{R_f}{R_1} \right] \left[\frac{R_3}{R_2 + R_3} \right] V_2$$

In circuit $R_1 = R_2 = R_3 = R$

\therefore The output voltage is

$$V_O = V_2 - V_1$$



$$A_{OL} = \frac{V_o}{V_d} = \frac{V_o}{V_1 - V_2} \rightarrow \infty$$

V_o is finite input voltage

$V_d = V_1 - V_2$ is forced (to be zero and thus)

$$V_i = V_1 - V_2 \quad \text{--- (i)}$$

This voltage appears across the resistor R_1 so the current is

$$i_1 = \frac{V_i}{R_1}$$

OP-amp Inverting terminal $I_B = 0$

$$\therefore i_1 = i_f$$

The voltage V_f appears across R_f and is

$$V_f = R_f \cdot i_f = R_f \cdot i_1 = R_f \cdot \frac{V_i}{R_1}$$

The voltage V_i , V_p , V_f and the output voltage V_o constitute a close loop.

$$V_o = V_i + V_d + V_f$$

$$V_o = V_i + V_f \left[A_{OL} \rightarrow \frac{V_o}{V_d} = \infty \quad \therefore V_d = 0 \right]$$

$$V_o = V_i + \left[1 + \frac{R_f}{R_1} \right]$$

$$A_{OL} = \frac{V_o}{V_i} \left[1 + \frac{R_f}{R_1} \right]$$

Name :- Ankita Balaso Ahot

08/10

॥ ज्ञान, विज्ञान आणि सुसंस्कार यांच्यासाठी शिक्षण प्रसार ॥

- शिक्षणमहर्षी डॉ. बापूजी साबुंबे

08093

Shri Swami Vivekanand Shikshan Sanstha Kolhapur's

VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Signature
of
Supervisor

Suppliment No. :

Roll No. : 8362

Class : BSC-III

Subject : Electronic

Test / Tutorial No. :

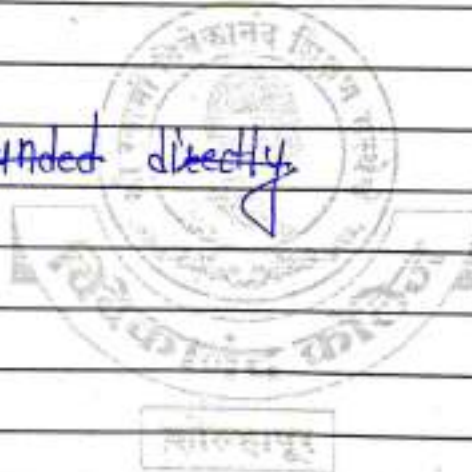
Div. :

Q1)

i) ~~b) triangular wave~~

2) ~~a) input is grounded directly~~

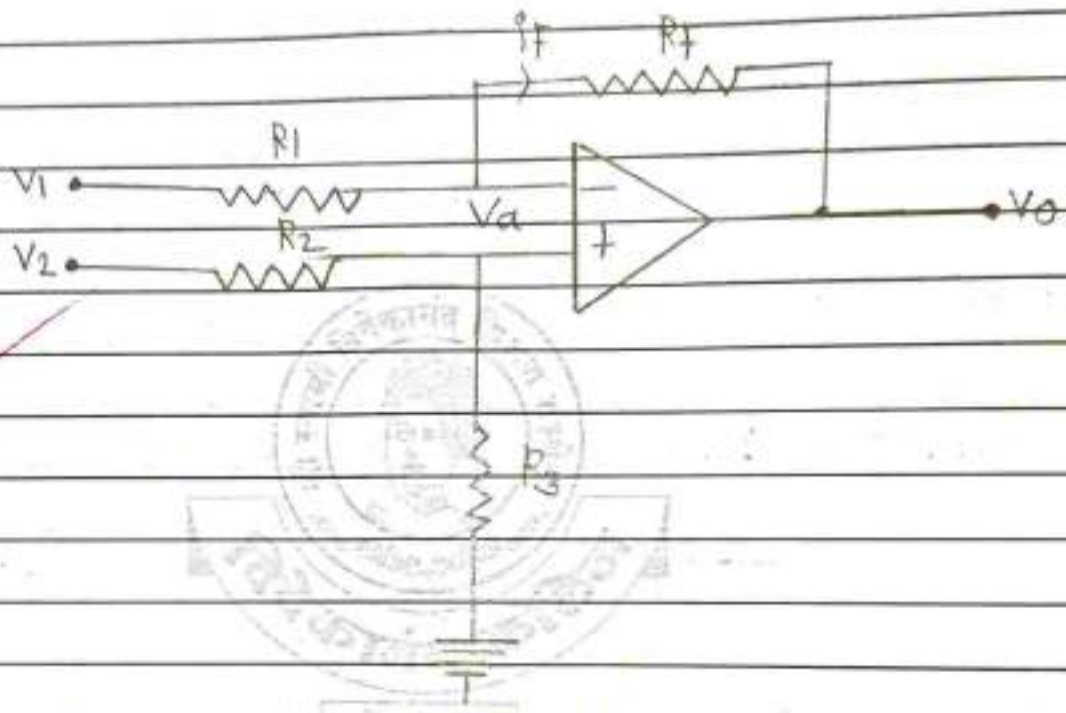
~~b)~~



Q2)
3)

Subtractor

Block dig. of op-Amp subtractor :-



Dig. shows op-Amp subtractor :

V_2 is grounded

$$\therefore V_2 = 0$$

then the circuit is, inverting op-Amp

then, the output of the inverting op-Amp

$$V_{o2} = -\frac{R_f}{R_1} \cdot V_i \quad \text{--- (i)}$$

V_1 is grounded

$$\therefore V_1 = 0$$

then the circuit is, noninverting op-Amp

$$\therefore V_{o2} = \left[\frac{1 + \frac{R_F}{R_1}}{\frac{R_2 + R_3}{R_1}} \right] V_2 \quad \text{--- (ii)}$$

from eqⁿ (i) and (ii)

using the superposition principle.

$$V_o = V_{o1} + V_{o2}$$

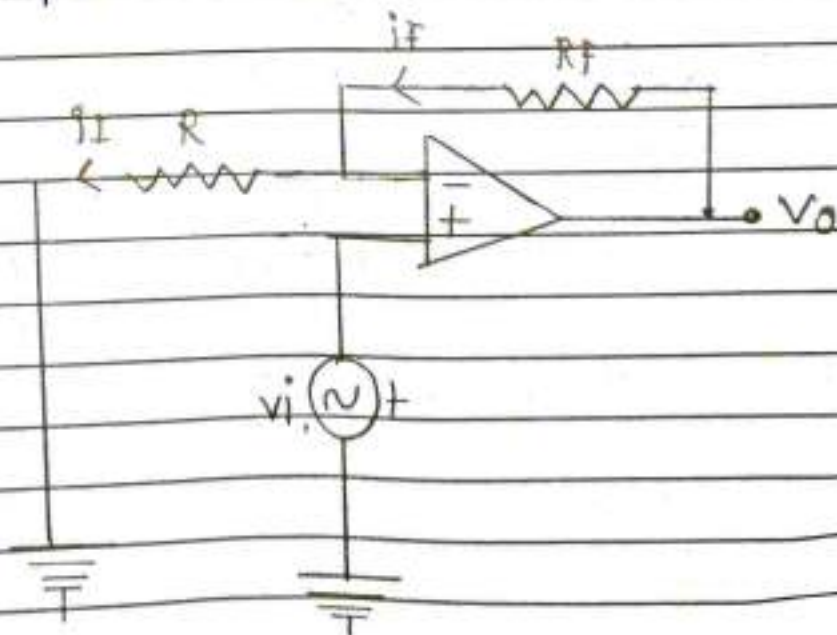
$$= \left[\frac{-R_F}{R_1} \right] V_1 + \left[\frac{1 + \frac{R_F}{R_1}}{\frac{R_2 + R_3}{R_1}} \right] V_2$$

In circuit $R_1 = R_2 = R_3 = R$

\therefore The output voltage is

$$V_o = V_2 - V_1$$

4) Non-inverting amplifiers :-



In non-inverting Amplifier,

for, The most widely used op-AMP configuration is non-inverting for an ideal op-AMP

$$AOL = \frac{V_o}{V_d} = \frac{V_o}{V_1 - V_2} = \infty$$

V_o is the finite input voltage.

$$\therefore V_o = V_1 - V_2$$

since,

the infinite offset input resistor R_i

$$\therefore V_1 = V_2$$

$$V_i = V_1 = V_2 \quad \text{--- (1)}$$

The voltage across resistor R_i and current i_1 is given by.

$$i_1 = i_f$$

for, an ideal op-AMP inverting.

$$\therefore I_B = 0$$

$$i_1 = \frac{V_i}{R_i}$$

The voltage V_f appears across R_f and is

$$V_f = R_f \cdot i_f = R_f \cdot i_1$$

$$R_f = \frac{V_f}{R_i}$$

Shri Swami Vivekanand Shikshan Sanstha Kolhapur's

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Div. :

The voltage v_i , v_d , v_f and the output voltage v_o constitute a closed loop.

Applying KCL.

$$v_o = v_i + v_d + v_f$$

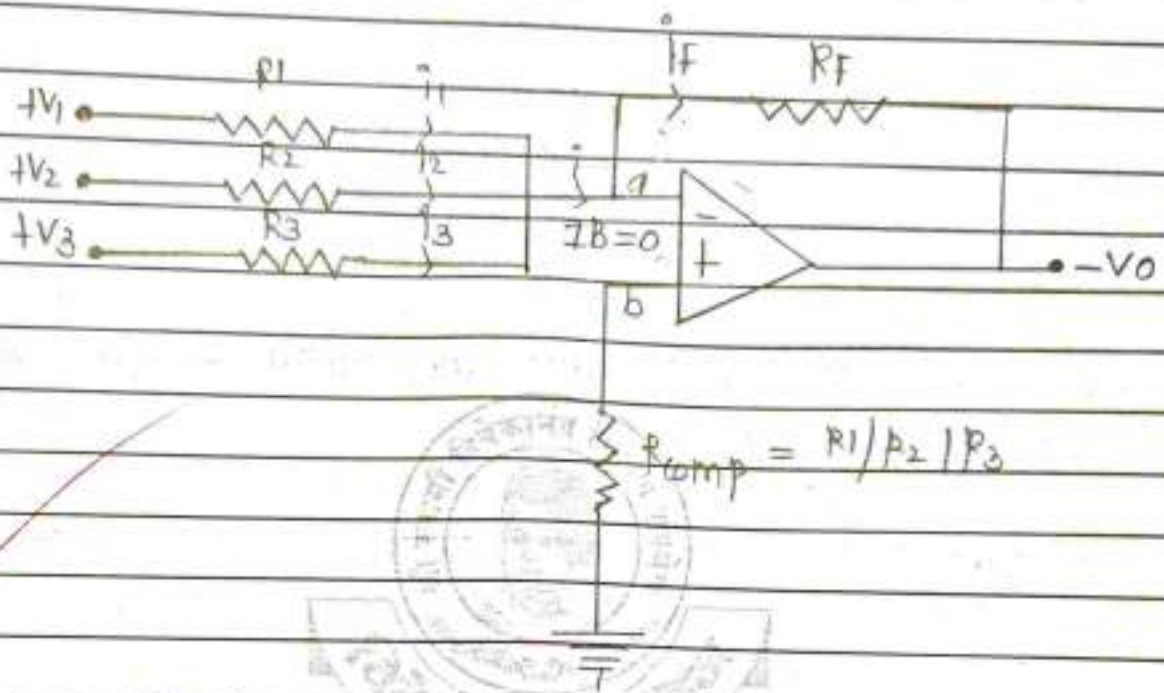
$$= v_i + v_f \quad [A_{OL} = \frac{v_o}{v_d} = \infty, \therefore v_d = 0]$$

$$v_o = (1 + \frac{R_f}{R_i}) v_i$$

$$A_{OL} = \frac{v_o}{v_i} = \left[1 + \frac{R_f}{R_i} \right]$$

1) Adder

1) Inverting :-



for, ideal op-amp

$$A_{OL} = \frac{V_o}{V_d} = \frac{V_o}{V_2 - V_1} = \infty$$

V_o is forced to be zero,

$$\therefore V_o = V_1 - V_2$$

$$\therefore V_1 = V_2$$

since,

infinite input impedance R_F .

$$I_B = 0$$

Applying KCL.

$$-i = I_B + i_f \\ = i_1 + i_2 + i_3 = i_f$$

$$I = \frac{V_1 - V_a}{R_1} + \frac{V_2 - V_a}{R_2} + \frac{V_3 - V_a}{R_3} = \frac{-V_o}{R_F}$$

$$= \frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} \quad [\because V_a = 0] = \frac{-V_o}{R_F}$$

In circuit $R_1 = R_2 = R_3$

$$\therefore V_o = -[V_1 + V_2 + V_3]$$

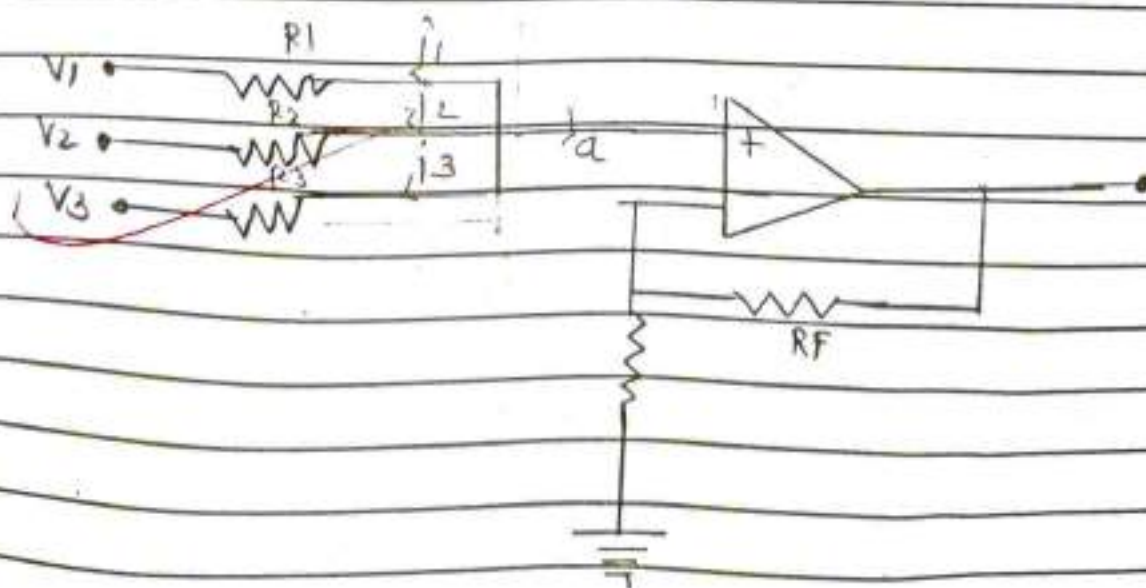
$$\therefore V_o = -R_F \left[\frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} \right]$$

In circuit, $R_1 = R_2 = R_3$

$$\therefore V_o = -[V_1 + V_2 + V_3]$$

\therefore The output voltage is equal to negative sum of all input.

2) Non-inverting :-



equation for node a.

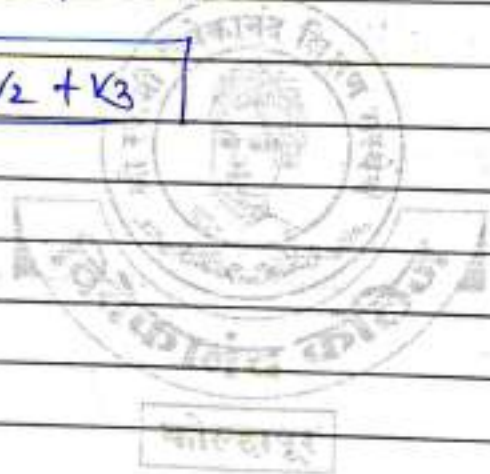
$$i_2 = i_1 \quad i = i_B + i_F \\ = i_1 + i_2 + i_3 = i_F$$

$$\frac{V_1 - V_a}{R_1} + \frac{V_2 - V_a}{R_2} + \frac{V_3 - V_a}{R_3} = \frac{-V_0}{R_1} + \frac{V_0}{R_F}$$

$$= \frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} = \frac{V_0}{R_F}$$

$$R_1 = R_2 = R_3 = R_F = R$$

$$V_0 = V_1 + V_2 + V_3$$



09/15

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- शिक्षणपट्टी डॉ. बापूजी साबुंबे

08227

Shri Swami Vivekanand Shikshan Sanstha Kolhapur's

VIVEKANAND COLLEGE, KOLHAPUR (AUTONOMOUS)

SUPPLIMENT

Signature
of
Supervisor

Subject: Electronic

Test / Tutorial No. :

Div. :

Suppliment No. :

Roll No. : 8361

Class : Bsc III

Q1.)

1) The output of a schmitt trigger is a
→ d) sine waveform

OX

2) Virtual ground of an op-amp means.

→

a) Input is grounded directly.

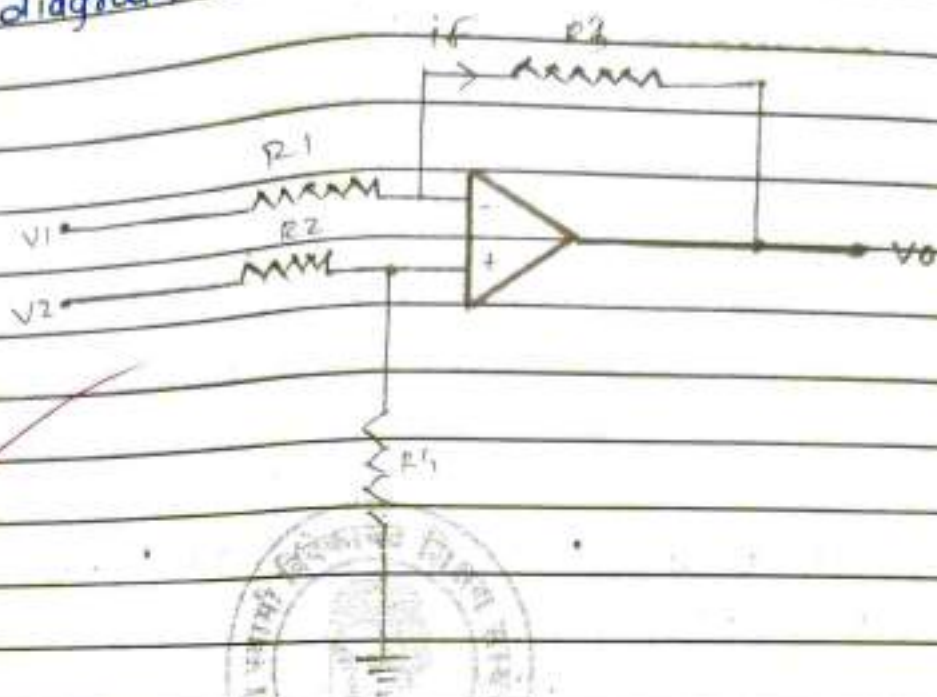
b) Input is not physically grounded but terminal voltage is zero due to the other terminal is connected to the ground due to op-amp properties.

O/✓

Q 2)

3)

→ Block diagram of op-amp.



Q 4

Fig. shows op-amp. substructure.

V_2 is grounded then the circuit is inverting op-amp. with its output ($V_2 = 0$)

$$V_0 = -\frac{R_f}{R_i} V_1 \quad \text{--- (i)}$$

V_1 is grounded

$$V_1 = 0$$

then the circuit is noninverting op-amp.

$$V_0 = \left(1 + \frac{R_f}{R_i}\right) V_a = \left(1 + \frac{R_f}{R_i}\right) \left(\frac{R_3}{R_2 + R_3}\right) V_2 \quad \text{--- (ii)}$$

from eqⁿ (i) and (ii)

using the superposition principle

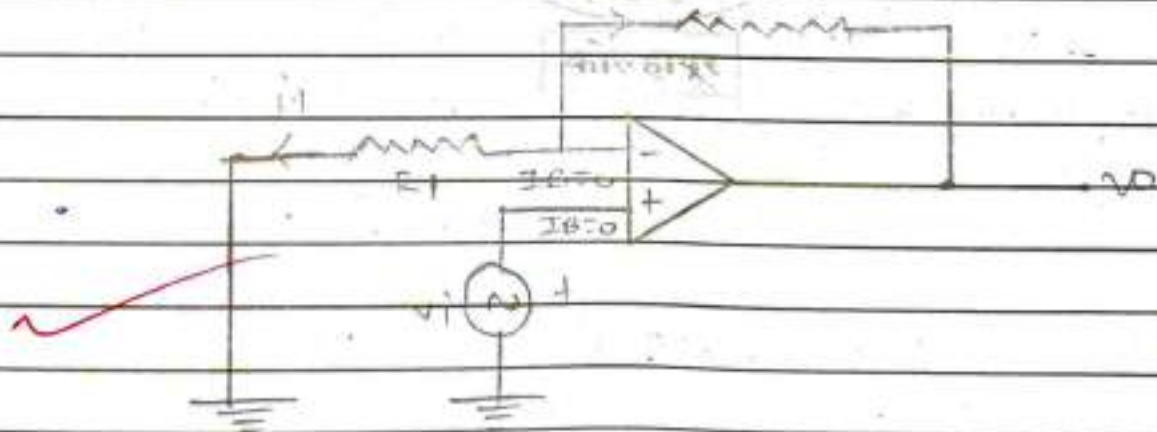
$$V_0 = V_1 + V_2$$
$$= \left[\frac{-R_f}{R_i} \right] V_1 + \left[\frac{1+R_f}{R_i} \right] \left[\frac{R_3}{R_2+R_3} \right] V_2$$

In circuit $R_1 = R_2 = R_3 = R$

\therefore The circuit voltage is

$$V_0 = V_2 - V_1$$

4) Non inverting amplifier -



In noninverting amplifier.

$$A_{OL} = \frac{V_0}{V_d} = \frac{V_0}{V_1 - V_2} = \infty$$

V_o is in finite input voltage
 $V_d = V_1 - V_2$ is forced to be zero and thus
 $V_i = V_1 - V_2 \quad \text{---} \quad \text{①}$

This voltage across the resistor R_i so the current

$$i_i = \frac{V_i}{R_i}$$

op-amp inverting terminals $I_B = 0$
 $i_i = i_f$

The voltage V_f across R_f and is

$$V_f = R_f \cdot i_f = R_f \cdot i_i = R_f \cdot \frac{V_i}{R_i}$$

The voltage V_i , V_d , V_f and the output voltage V_o constitute a closed loop.

Applying KVL to this closed loop.

$$V_o = V_i + V_d + V_f$$

$$V_o = V_i + V_f \quad [A_{OL} = V_o/V_d = \infty \therefore V_d = 0]$$

$$V_o = V_i \left[1 + \frac{R_f}{R_i} \right]$$

$$A_{OL} = \frac{V_o}{V_i} = \left[1 + \frac{R_f}{R_i} \right]$$

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08233

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Test / Tutorial No. :

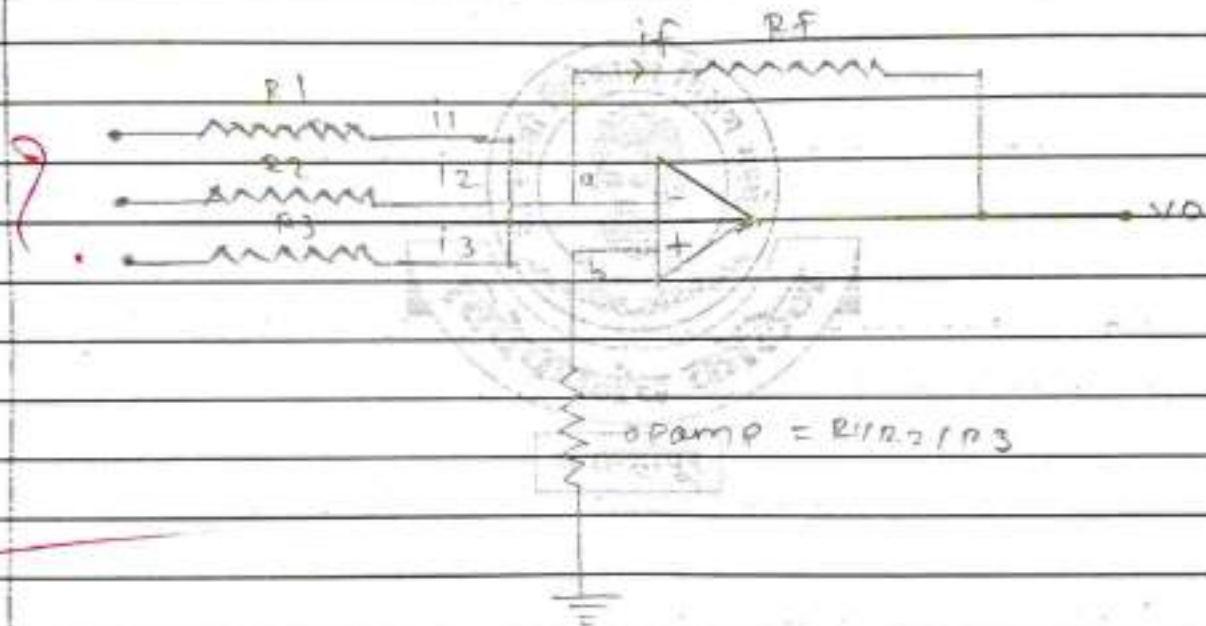
Div. :

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Roll No. : 8361

Class : BSc III

1)



for ideal op-amp.

$$A_{OL} = \frac{V_o}{V_d} = \frac{V_o}{V_2 - V_1} = \infty$$

V_o is forced to be zero.

$$V_o = V_1 - V_2$$

$$\therefore V_1 = V_2$$

since:
 infinite input impedance R_f
 Applying KCL:

$$i = i_B + i_f$$

$$\Rightarrow i_1 + i_2 + i_3 = i_f$$

$$i = \frac{v_1 - v_0}{R_1} + \frac{v_2 - v_0}{R_2} + \frac{v_3 - v_0}{R_3} = \frac{-v_0}{R_f}$$

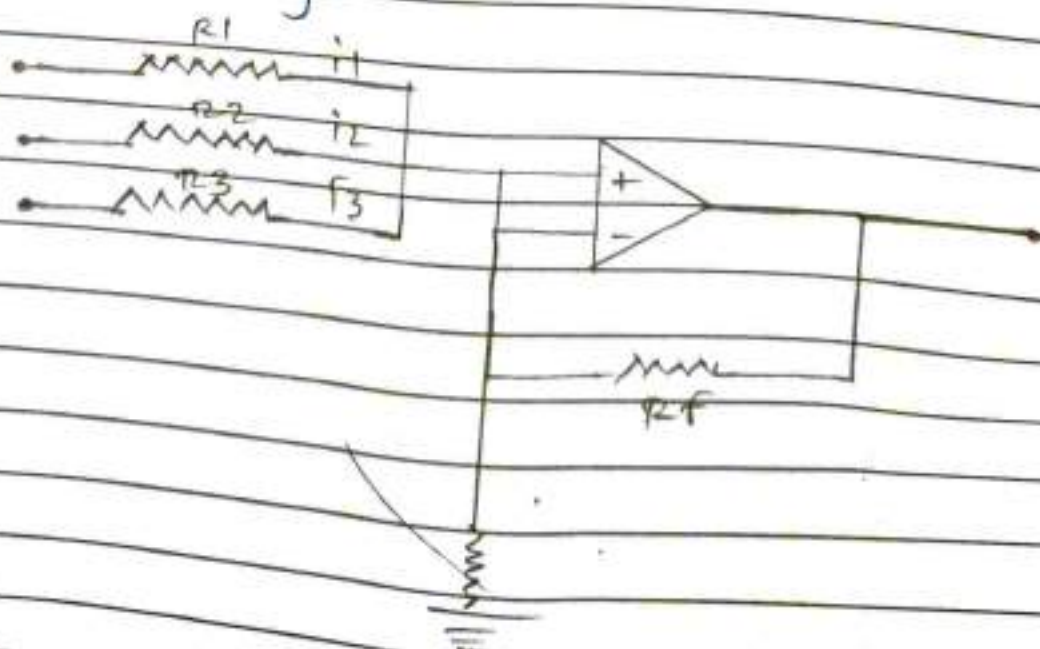
$$\frac{v_1}{R_1} + \frac{v_2}{R_2} + \frac{v_3}{R_3} = \frac{-v_0}{R_f}$$

$$v_0 = -R_f \left[\frac{v_1}{R_1} + \frac{v_2}{R_2} + \frac{v_3}{R_3} \right]$$

If in the circuit $R_1 = R_2 = R_3 = R_f$ the output voltage becomes

$$v_0 = -(v_1 + v_2 + v_3)$$

2) Non inverting



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Q.1

i) b) ~~127~~ -128 to 127

ii) ~~Hex~~ b) ACD

Q.2

i)

→ Advantages

i) It is easier and less time consuming than ALP

ii) It is easy to modify and update

iii) user has facility to use function library

iv) C language generated code is transferable from one to another microcontroller.

Data type	Size in bit	Data range
1) unsigned char	8-bit	0 to 65536 255
2) (signed) char	8-bit	-128 to +127
3) unsigned int / short	16-bit	- 32768 ^{0 to 65536} to + 32767
4) (signed) int / short	16-bit	-32768 to +32767
5) Sbit	1-bit	SFR bit addressable only
6) bit	1-bit	RAM bit addressable area only
7) sfr	8-bit	SFR address 80H to FFH

ii) C-Program -

```
#include <reg51.h>
```

```
mybit = P1^5
```

```
void delay (void)
```

```
void main (void)
```

```
{
```

```
while (1)
```

```
{
```

```
P1 = 0x00FF;
```

```
delay ();
```

```
P1 = 0x00;
```

```
delay ();
```

```
}
```

```
}
```

```
void delay ()
```

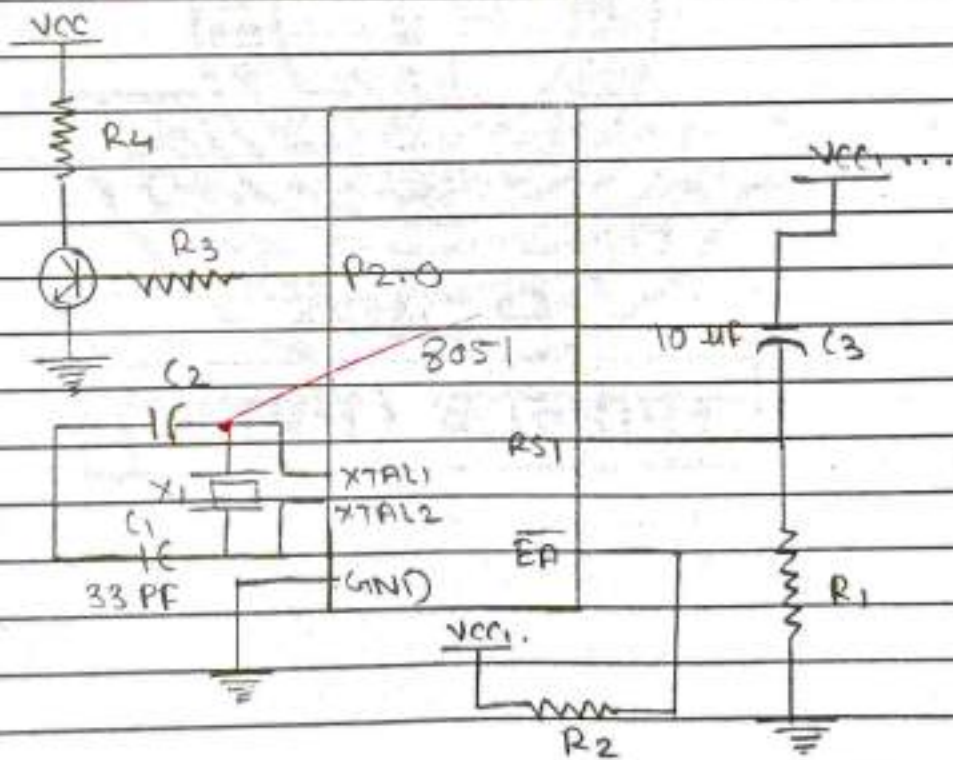
}

```

TMOD = 0x01;
TH0 = 0x03;
TL0 = 0xFF;
TR0 = 1;
while (TF0 == 0);
TR0 = 0;
TF0 = 0;
}

```

iv) Interfacing Diagram of LED.



2

C-Program -

```
#include <REGX51.H>
sbit LED = P0^P2^0
void delay (void)
void main (void)
```

```
{
  while (1)
  {
```

```
    LED = 1;
    delay ();
    LED = 0;
    delay ();
```

```
  }
}
```

```
void delay ()
```

```
{
```

```
  TMOD = 0x01;
```

```
  TH0 = 0x00;
```

```
  TLO = 0x00;
```

```
  TR0 = 1;
```

```
  while (TF0 == 0);
```

```
  TR0 = 0;
```

```
  TF0 = 0;
```

```
}
```

Akanksha santosh shinde

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Div. :

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Roll No. : 8371

Class : Bsc III

Q 1)

1) Data range for signed char data type is
-128 to +127

2) The output of Thumbwheel switch is in
Hex form

(Q 2)

- 1) advantages of embedded C — consuming
- i) it is easier and less time consuming than ALP.
 - ii) easy to modify and update.
 - iii) the users has facility to use a function library.
 - iv) The embedded C language generates code is transferable ~~code~~ for one or other microcontroller.

data types in C —

The C language provided all the data type of standard C data types. It also provides some additional data types which are related to 8051 micro-controllers. Data types a programming languages helps us to declaring variable in programs.

The following table shows most widely used data types.

Sr No.	Data types	size in bits	Data range
1	unsigned char.	8-bit	0 to 255
2	(signed) char.	8-bit	-128 to +127
3	unsigned int/char	16-bit	0 to 65535
4	(signed) int/char	16-bit	-32768 to +32767
5	SFR s bit	1-bit	SFR bit addressable only
6	bit	1-bit	RAM bit addressable only
7	SFR	8-bit	SFR address 00H to FFH. i.e. RAM location whose address from 00H to FFH

a) write an 8051-C generate square wave on port P1 using time delay.

```
#include <REGX51.H>
mybit = P1.5;
void delay (void)
void main (main)
```

```
{
```

```
while(1)
```

```
{
```

```
P1 = 0xFF;
```

```
delay ();
```

```
P1 = 0x00;
```

```
delay ();
```

```
}
```

```
}
```

```
void delay ()
```

```
{
```

```
TMOD = 0x01;
```

```
TH0 = 0x03;
```

```
TL0 = 0xFF;
```

```
TR0 = 1;
```

```
while (TR0 = 0);
```

Pretana Pradeep Shirke

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: Bsc.TY

Subject : 8051 microcontroller and embedded-C

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Q.1

1) Data range for signed char data type is -128 to +127

2) The output of Thumbwheel switch is in Hex form.

Q.2

1)

→ Advantages of embedded-C over assembly language:

1) Assembly language is tedious and time consuming but embedded-C language is less time consuming than ALP.

2) ALP has no function library facility but embedded-C has facility to use function library.

3) Program updating and modification is complicated in assembly language but it is easy to modify and update program in embedded-C.

4) The code generation in assembly language is not easily portable to another microcontroller but in embedded-C it is easy to transfer data from one to other microcontroller.

Tabulate of various Data type:

Sr No.	Data type	Data size range of bit	Data range.
1	Unsigned char	8-bit	0 to 255
2	signed char	8-bit	- 128 to +128
3	Unsigned int	16-bit	- 32768 to +32767
4	S-bit	1-bit	SFR ^{bit} function is addressable only
5	bit	1-bit	RAM addressable bit area only
6	SFR	8-bit	SFR: address 80H to FFH ^{access} i.e. whose RAM address from 80H to FFH.

2)

→

```
#include <reg51.h>
```

```
mybit = P1^5;
```

```
void delay(void);
```

```
void main(void)
```

```
{
```

```
while(1)
```

```
{
```

```
P1 = 0xFF;
```

```
delay();
```

```
P1 = 0x00;
```

```
delay();
```

```
}
```

```
}
```

```
void delay()
```

```
{
```

```
TMOD = 0x01;
```

```
TH0 = 0x00;
```

```
TLO = 0xFF;
```

```
TR0 = 1;
```

```
while(TFO == 0);
```

```
TR0 = 0;
```

```
TFO = 0;
```

```
}
```

Sakshi Tushar Bhopale.

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Subject : Electronics (I)

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08
10

i) Data range for signed char data type is
-128 to 127

ii) The output of thumbwheel switch is in Hex
form.

i)

Advantages of embedded C over ALP

- i) ALP is tedious and time consuming but embedded C languages is less than time consuming than ALU.
- ii) ALP has no function library facility but embedded C has facility to use function library.
- iii) Program updating and modification is complicated in ALP but in embedded C, modifying and update is easy.
- iv) The code generation in ALP is not easily portable in another microcontroller but in embedded C it is easy to transfer data from one to another microcontroller.

Sr. No	Data type	Size of bit	Data range
1.	unsigned char	8 bit	0 to 255
2.	signed char	8 bit	-128 to +128
3.	unsigned int.	16 bit	-32768 to +32767
4.	s bit	1 bit	SFR bit is addressable only
5.	bit	1 bit	RAM area addressable only
6.	SFR	8 bit	SFR address 80H to FFH i.e. whose RAM address from 80H to FFH

ii)

```
#include <REGX51.H>
void delay (void)
void main (main
```

```
#include <REGX51.H>
```

```
mybit = P1^5 ;
```

```
void delay (void) ;
```

```
void main (void)
```

```
{
```

```
while (1)
```

```
{
```

```
P1 = 0xFF ;
```

```
delay () ;
```

```
P1 = 0x00 ;
```

```
delay () ;
```

```
}
```

```
}
```

```
void delay ()
```

```
{
```

```
TMOD = 0x01 ;
```

```
TH0 = 0x00 ;
```

```
TLO = 0xFF ;
```

```
TR0 = 1 ;
```

```
while (TF0 == 0) ;
```

```
TR0 = 0 ;
```

```
TF0 = 0 ;
```

```
}
```

Name :- Ankita Balaso Khot

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Class : BSc-III

Subject : Electronics

Test / Tutorial No. :

Div. :

Q1)

i) B) -128 to $+127$

i) ~~Hex B) BcD~~

Q2)

i) * Advantage of embedded C-over assembly language

i) It is easily and less time consuming than APL.

ii) It is easy to modify and update.

iii) Vsee has use to function library.

iv) C-language generated code for one to other microcontrollers.

* Tabulate various data type in 8051-C

St.No	Data type	size in bit	Data range
1.	unsigned char	8-bit	0 to 255
2.	(signed) char	8-bit	-128 to +127
3.	unsigned int/ short	16-bit	0 to 65536
4.	(signed) int/ short	16-bit	-32768 to +32767
5.	sbit	1-bit	SFR address only
6.	Bit	1-bit	RAM address area only.
7.	SFR	8-bit	SFR address 80H to FFH.

ii)

```
#include <regx51.h>  
mybit pins;
```

```
void dely (void);  
void main (main)
```

```
{  
  {  
    p1 = 0xff;  
    delay ();  
    p1 = 0x00;  
    delay ();  
  }  
}
```

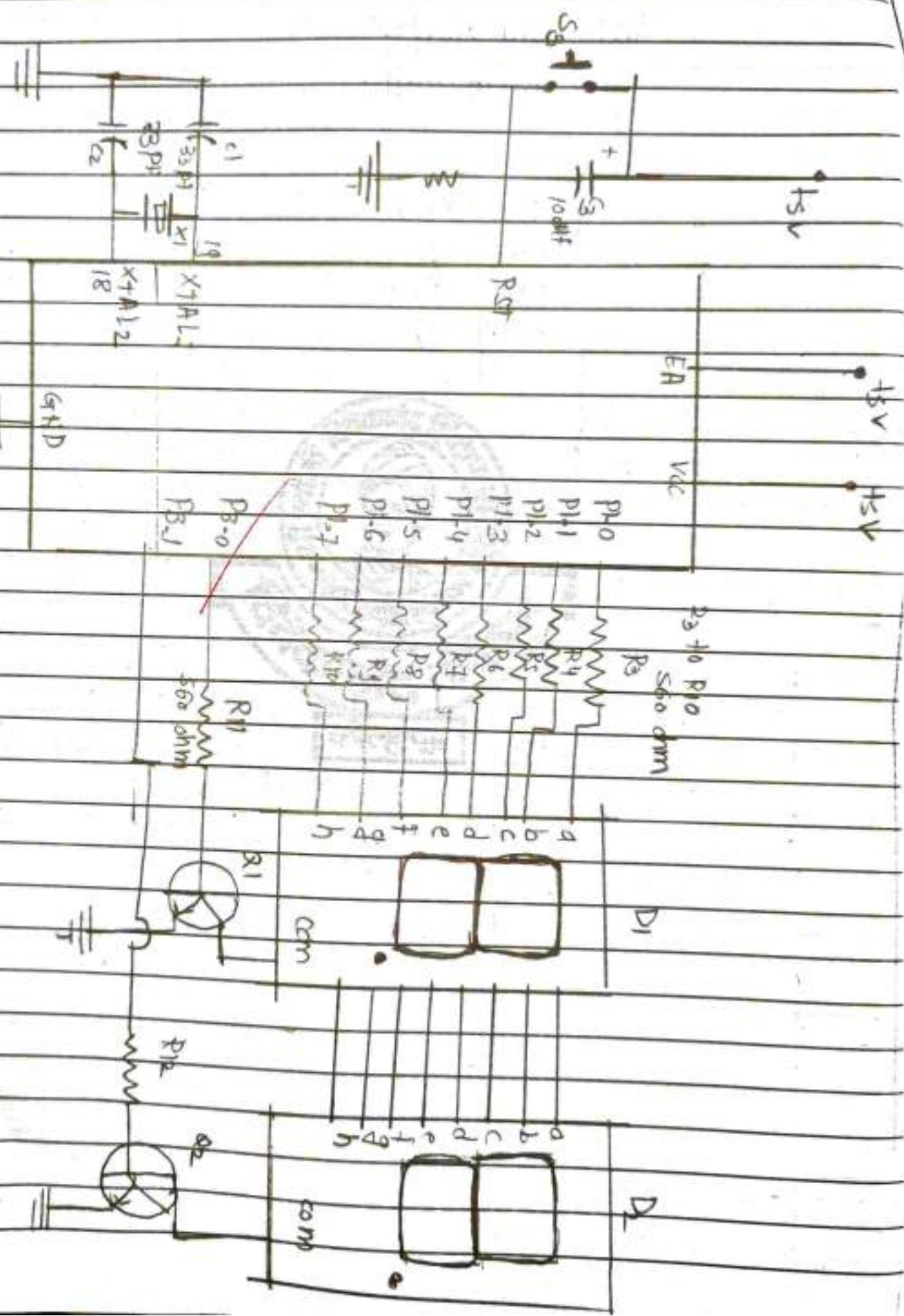
```
void delay ()
```

```
{  
  TMOD = 0x01;  
  TH0 = 0x03;  
  TL0 = 0xff;  
  TR0 = 1;  
  while (TF0 == 0);  
  TR0 = 0;  
  TF0 = 0;  
}
```

4

iii)

Seven segment Display with 8051



Name :- Ankita Balago khot

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Program :-

```
#include <regx510h>
```

```
sbit a = P3^0;
```

```
sbit b = P3^1;
```

```
void main ()
```

```
{  
  unsigned char seq_code [] = { 0xBF, 0x06, 0x5b, 0x4F  
                                0x66, 0x6d, 0x7d,  
                                0x07, 0x7f, 0x6f };
```

```
  unsigned int i, j, k;
```

```
  while (1)
```

```
  {  
    for (i=0; i<100; i++);
```

```
    {  
      a = 1;
```

```
      b = 0;
```

```
      P1 = seq_code [i/10];
```

```
      for (k=0; k<35000; k++);
```

```
      a = 0;
```

```
      b = 1;
```

4

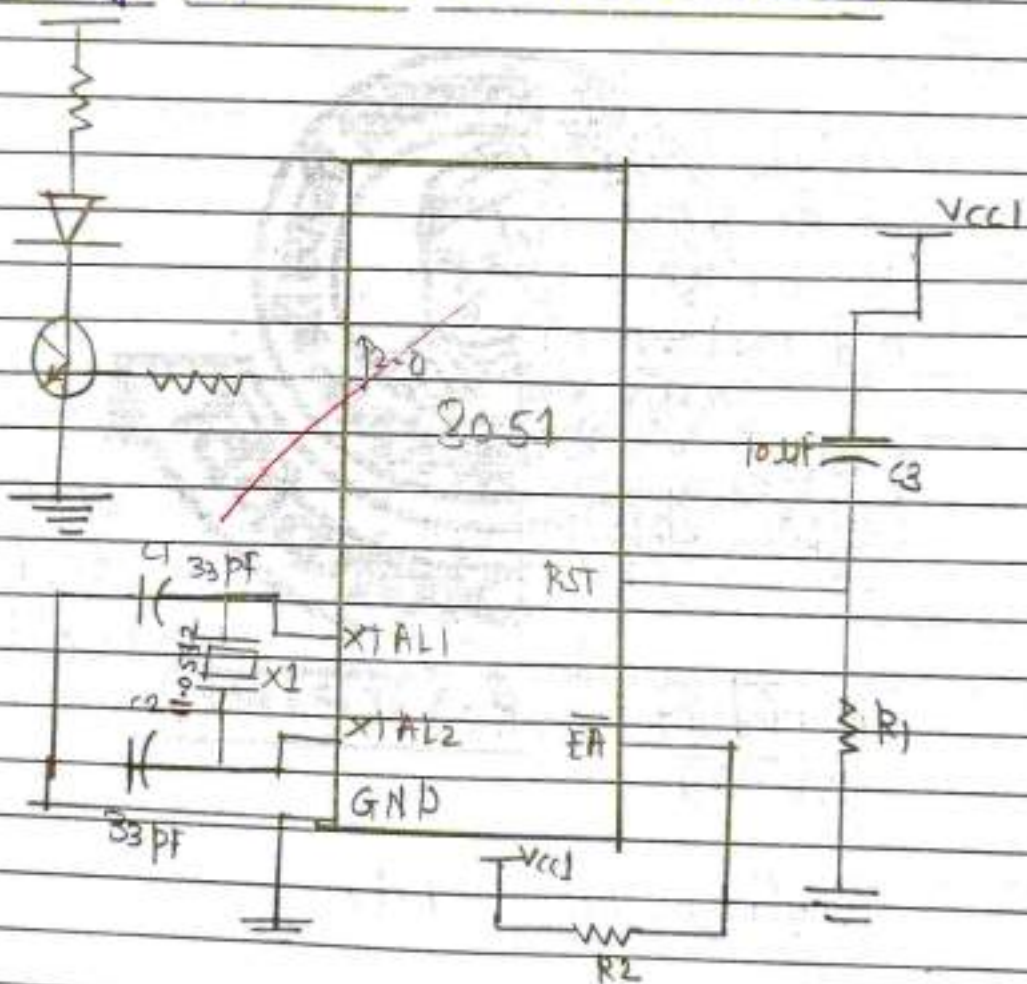
```

P1 = Seq. code [i % 10];
for (k=0; k < 35000; k++);
}
}
}

```

Interfacing LED with 8051 microcontroller.

PM



```
#include <regx51.h>
sbit LED = P2^10
void Delay (void)
void main (main)
```

```
{
  while(1)
  {
    LED = 1;
    delay ();
    LED = 0;
    delay ();
  }
}
```

whit void delay

```
{
  TMOD = 0x01;
  TH0 = 0x00;
  TL0 = 0x00;
  TR0 = 7;
  while (TF0 == 0);
  TR0 = 0;
  TF0 = 0;
}
```

Sandeep Jaysing Patil.

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Subject : Electronics

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(Instrumentation)

Div. :

Q.1

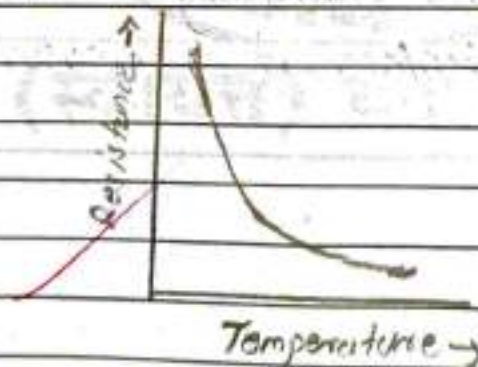
1) Passive transducers require external power source for their operation.

2) Which of the following transducers is used for displacement measurement?
⇒ LVDT.

Q.2

1) Thermistor

- ① Thermistor is temperature sensitive device.
- ② If the temperature varies then the resistance of thermistor either increases or decreases.
- ③ By using this principle thermistor is used as temperature sensor.
- ④ Semiconductor material are used in thermistor.
- ⑤ Because of semiconductor, the $\#$ resistance of thermistor is slightly varies with temperature more than the normal resistance.
- ⑥ Thermistor are classified into two types:
 - ① Negative temperature coefficient (NTC)
 - ② Positive temperature coefficient (PTC)
- ⑦ NTC thermistor characteristics are very common as shown in figure.



- ⑦ In NTC thermistor, resistance decreases as the temperature increase as following equation

$$R_T = R_0 e^{B \left(\frac{1}{T} - \frac{1}{T_0} \right)}$$

Features of thermistor

- ① Size is about from 0.125 to 1.5 mm.
- ② Temperature range is from -100°C to 300°C .
- ③ Model types - Bed type, rod type and disc type.

2) Construction and working of LVDT.

LVDT stands for Linear variable differential transformer. It is most widely used transducer that converts linear motion into the electrical signal.

* Construction of LVDT

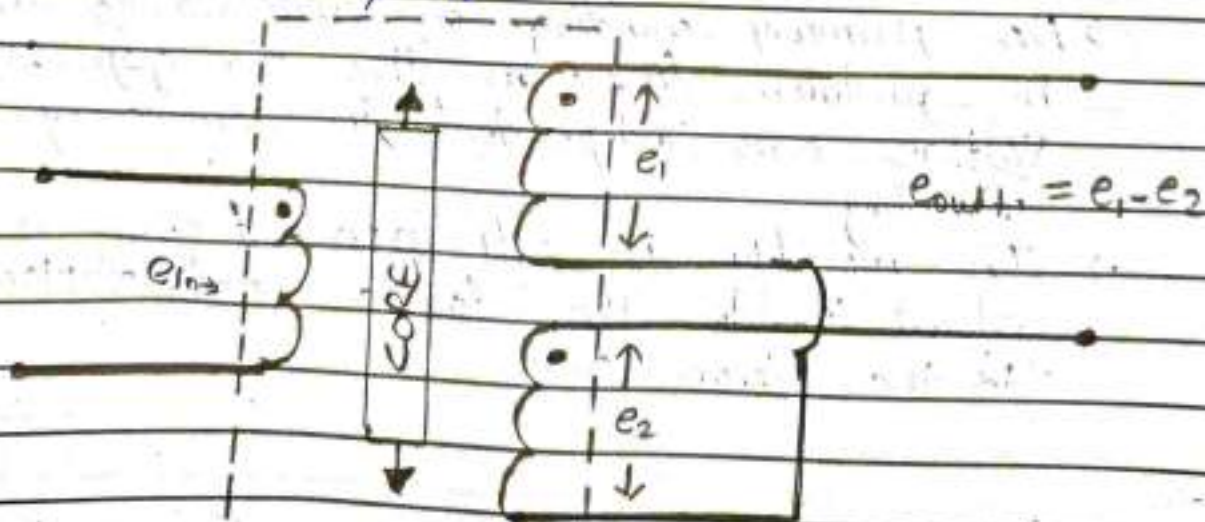
- It consists of primary with winding as well as two secondary winding. These are S_1 and S_2 which wound on a cylindrical former.
- Both the secondary winding secondary windings have equal number of turns and they are identically placed on either sides of primary winding.
- The primary winding is connected to an AC produced flux in the air gap and voltage are induced in secondary winding.
- In movable iron soft iron core is placed inside the former and displacement to the iron core.

Working of LVDT

Case I: In the formation of When the core is at null position both the secondary winding is equal to so the induced emf is equal to the both winding so it is shows that no displacement takes place.

Case II: When the core is at upward position (for the upward displacement and reference point). In this case the flux linking with secondary coil S_1 is more as compared to linking with S_2 . Due to this e_1 will be more than of e_2 . That is output voltage e_{out} is positive.

Case III: When the core is at downward position (for downward displacement). In this case magnitude of e_2 will be more as that of e_1 . Due to this output will be negative and shows output e_{out} downward of reference point.



Pradnya Prashant Jadhav

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Class : BSC-III

08

10

Q 1

1) Passive

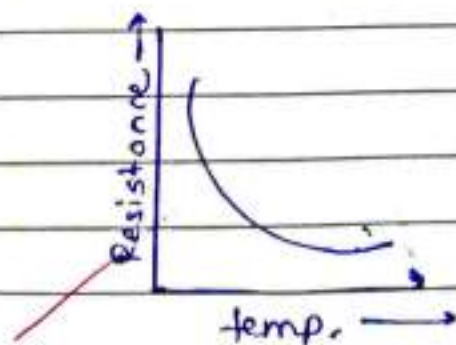
2) LVDT



2

1) Thermistor

- 1) Thermistor is a temperature sensitive device.
- 2) If the temperature varies, then the resistance of the thermistor either increases or decreases. By using the property we can use it as temperature sensor.
- 3) Semiconductor material are used in thermistor prepared from oxide of chromium, cobalt, nickel, manganese, sulphides of iron, aluminium or copper.
- 4) Because of semiconductor, resistance of the thermistor varies significantly with temperature. Co-efficient thermistor, positive temperature co-efficient thermistor.
- 5) The characteristics of NTC thermistor is more common, which is shown in fig.



The NTC thermistor the resistance decreases as the temp. increases. according, the following expression.

$$R_T = R_{0e}^{\beta} \left(\frac{1}{T} - \frac{1}{T_0} \right)$$

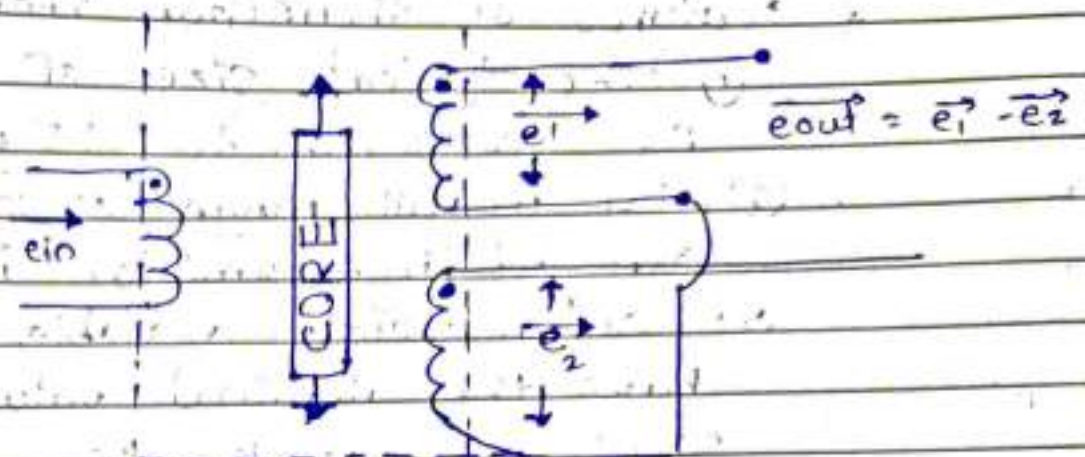
* Features of thermistor thermometer.

- ① The typical size of a thermistor is 0.125 mm to 1.5 mm.
- ② The useful range of temp. that we can get in thermistor is -100°C to $+300^{\circ}\text{C}$.
- ③ Commercial available thermistors have the nominal values of 1k, 2k, 10k, 20k, 100k, etc.
- ④ Thermistors are available in different type; bead type, rod type, disc type, etc.

2) Construction and working of LVDT:-
Construction:-

- ① The transformer consists of a primary winding P & two secondary windings S_1 & S_2 wound on cylindrical former.
- ② Both the secondary windings have equal number of turns & are identically placed on the either side of primary winding.
- ③ A primary winding is connected to an AC source produces a flux in the air gap & voltage are induced in secondary winding.
- ④ A movable soft iron induced iron core is placed inside the former and displacement to be measured is connected to the iron core.

WORKING OF LVDT:



* Case I :-

when the core is at null position flux linking with both the secondary windings is equal so the induced emf is equal in both the winding so for no displacement the value of output e_{out} is zero as e_1 & e_2 both are equal. So it shows that no displacement takes place.

* Case II :-

when the core is moved to upward null position. In this case the flux linking with secondary winding S_1 is more compared to flux linking with S_2 . Due to this e_1 will be more as that of e_2 .

* Case III :-

when the core is moved to downward null position. In this magnitude of e_2 will be more as that of e_1 due to this output e_{out} will be negative & shows that output to downward of reference point.

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- शिक्षणवर्धी डॉ. बापूजी साबुळे

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Subject: Electronics

Test / Tutorial No.: Internal Exam

Div.:

Suppliment No. :

Roll No. : 8369

Class : BSC - TY Sem-V

7/10

Q1

1. ~~Passive~~

2. ~~LVDT~~



Q2

1. Thermistor -

Thermistor is a temp sensitive device. If the temp varies then the resistance of the thermistor either increases or decreases. By using this property we can use it as a temperature sensor. In thermistor the semiconductor materials are used.

Thermistor are classified into two types are negative temperature coefficient thermistor and positive temp coefficient thermistor. In NTC thermistor the resistance decreases as the temperature increases, according to the following expression.

$$R_T = R_0 \cdot B \left(\frac{1}{T} - \frac{1}{T_0} \right)$$

Features of Thermistor

① The typical size of a thermistor is 0.125 mm to 1.5 mm. The useful range of temperature that we can get in thermistor is 100°C to 300°C. Commercially available thermistor have nominal values of 1k, 2k,

10k, 20k, 100k, etc. This value indicates that the resistance value at the temperature of 25°C. Thermistor are available in different models bead type, rod type, disc type etc.

Bridge circuit formation using Thermistor

When $R_T, R_1 = R_2, R_3$, R_1, R_2, R_3 resistors are fixed value resistors then the output voltage can be varied due to change in resistance R_T

$$V_{AB} = \frac{R_T}{R_T + R_3} * V_S \quad \& \quad V_{AD} = \frac{R_1}{R_1 + R_2} * V_S$$

2. Construction and working of LVDT -

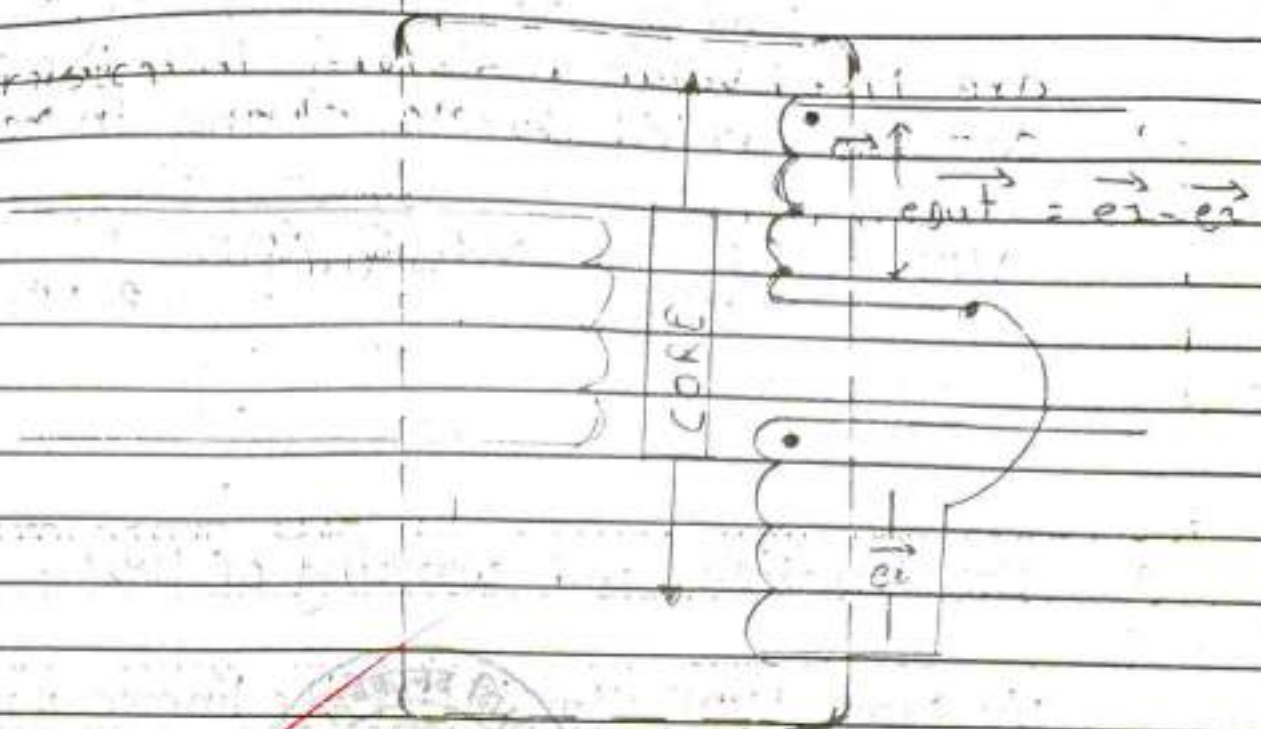
The term LVDT stands for the linear variable differential transformer. It is the most widely used inductive transducer that converts the linear motion into the electrical signals.

Construction of LVDT -

Main Features of construction areas:

- * The transformer consists of a primary winding P and two secondary windings S_1 and S_2 wound on a cylindrical former.
- * Both the secondary windings S_1 and S_2 wound on tapers and are identically placed on the either side of primary winding.
- * The primary winding is connected to an AC source which produces a flux in the air gap and voltages are induced in secondary winding.

Principle of operation and working -



Working -

Case I - when the core is at null position when the core is at null position then the Flux linking with both the secondary Windings is equal so the induced e_{out} is equal in both the windings so for no displacement the value of output e_{out} as e_2 both are equal

Case II - when the core the Flux linking with secondary winding S_1 is more as compared to Flux linking with S_2

Case III - when the core is moved to downward of Null position displacement to the downward of reference point In this case magnitude of e_2 will be more as that of e_1 .

Ketan Ashok Kumbhar

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Class : BSC III

$\frac{10}{14}$

Q 1)

1) transducers require external power source for their operation.

→ a) passive

2) Which of the following transducers is used for displacement measurement?

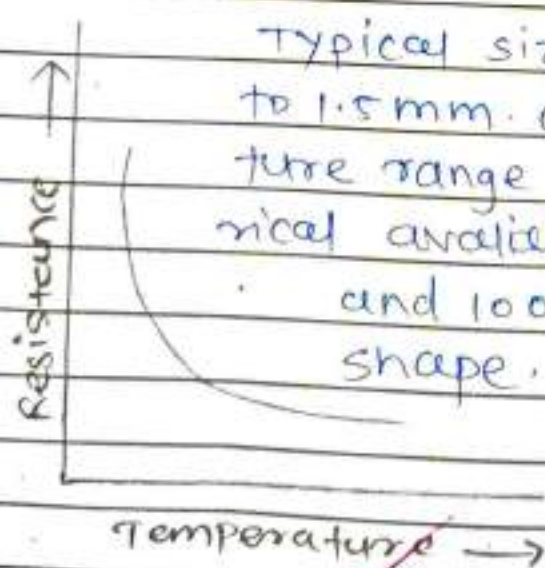
→ c) LVDT

Q 1)

1)

→ Thermistors -

- i) Thermistor is a sensitive device.
 - ii) Its temperature varies, resistance of thermistor increases or decreases.
 - iii) In thermistor semiconductor materials are used.
 - iv) semiconductor materials are prepared from oxide, copper, nickel, manganese, aluminium. The thermistor temperature varies generally, significantly with temp more than normal resistance.
- The thermistor is classified into two types: negative temperature coefficient and positive temperature coefficient. In negative temperature, in different thermistor, resistance decreases in temperature increases according to following formula.
- $$R_T = R_{0e} f \left[\frac{1}{T} - \frac{1}{T_0} \right]$$



Typical size of thermistor is 0.125 mm to 1.5 mm. connected to used temperature range is -200°C to 300°C commercial available in values 1K, 2K, 10K, 20K and 100K shape bead shape rod shape.

Advantage - The thermistor is relatively low cost and small size.

2)

→ LvdT

construction :- The main features of construction are. The transformer the primary winding P and two secondary winding S_1 and S_2 wound on cylindrical former.

i) The secondary winding is equal to the number of turns and identically placed in primary winding.

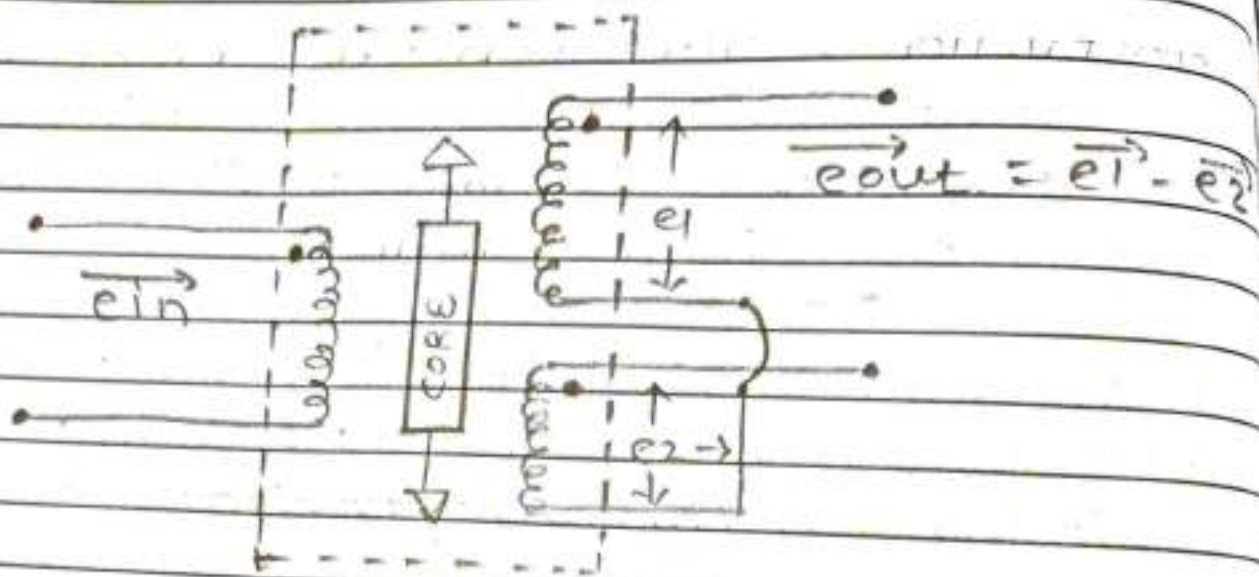
ii) The primary winding is connected to Ac source and ~~so~~ Ac source produce flux in air gap and voltage induced in secondary winding.

iii) The movable soft iron core is inside in the core and displacement in iron core.

principle operation -

The primary winding is connected to Ac source and produce voltage secondary wdt in secondary windings S_1 is equal to e_1 and S_2 is equal to e_2 .
The output voltage is,

$$V_{out} = e_1 - e_2$$



Working :-

Case I) when the core is an null position (No displacement) then the flux linking with the both secondary windings equal then the induced emf is equal in both the winding so no displacement the value of e_{out} is zero the e_1 and e_2 both equal. It is shows no displacement to place.

Case II):

when the core is an upward direction (displacement upward to resistance point. then the flux linking with the secondary winding s_1 is more as compared to flux linking with s_2 . due to e_1 is more as compared e_2 . due to e_{out} is positive.

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Case III):

When the core is an downward direction (Displacement downward to reference point) then the flux of magnitude of e_2 due to this e_{out} will be ~~negative~~ and shows the output downward to reference point.

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16
16

Q.1)

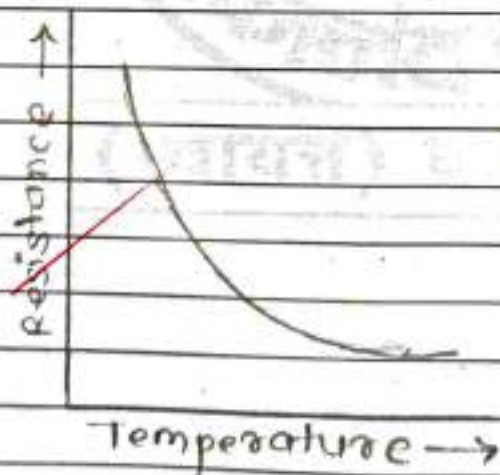
1) Passive transducers requires external power source for their operation.

2) LXDT

Q3)

1) Thermistor

- 1) Thermistor is the temperature sensitive device.
- 2) If the temperature varies, then the resistance of the thermistor either increases or decreases.
- 3) By using this property, we can use it as a temperature sensor.
- 4) In thermistor, the semiconductor materials are used. Because of semiconductor, resistance of the thermistor varies significantly with temperature, more than the normal resistance.
- 5) Thermistors are classified into two types.
Negative Temperature Coefficient Thermistor
Positive Temperature Coefficient Thermistor.
- 6) Features of thermistor thermometer



Typical size = 0.125 mm to 1.5 mm

Temperature range = 100°C to 300°C

Models = bead type, rod type, disc type

Advantages : Low cost

small size.

Formula: $R_T = R_{oe}^P (1/T - 1/T_0)$

2) LVDT

LVDT stands for Linear Variable Differential Transducer.

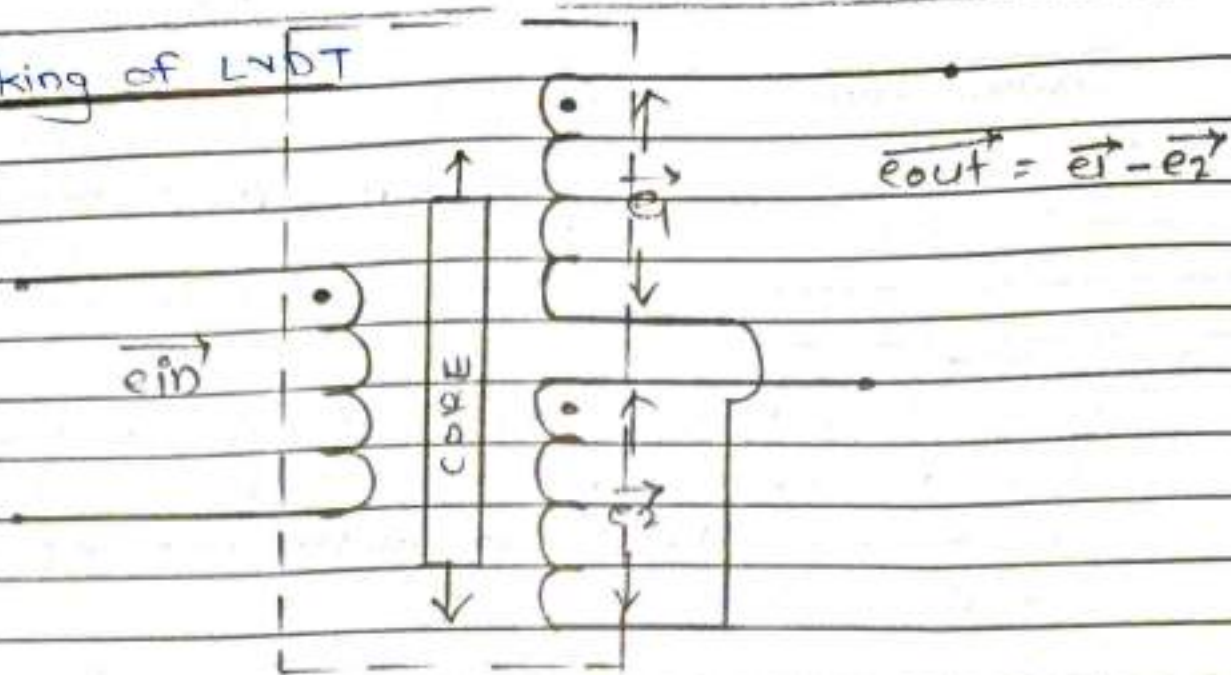
It converts the linear motion into the electrical signals.

Construction of LVDT

Main features of LVDT

- 1) The transformer consists of a primary winding P_1 and two secondary winding S_1 and S_2 wound on a cylindrical former.
- 2) Both the secondary windings have equal number of turns and are identically placed on the either side of primary winding.
- 3) The primary winding is connected to an AC source which produces a flux in the air gap and voltages are induced in secondary winding.
- 4) A movable soft iron core is placed inside the former and displacement to be measured is connected to iron core.

Working of LVDT



Case I: When the core is at null position

When the core is at null position then the flux linking with both the secondary winding is equal so the induced emf is equal in both the winding so it is shown that no displacement took place.

Case II: When the core is moved to upward of null position

In this case, the flux linking with secondary winding S_1 is more as compared to the linking with S_2 . Due to this e_1 will be more as that of e_2 . Due to this output voltage e_{out} is positive.

Case III: When the core is moved to downward of null position.

In this case, magnitude of e_2 is will be more as that of e_1 . Due to this, output will be negative and shows output downward of reference point.

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Q 1

1 Passive

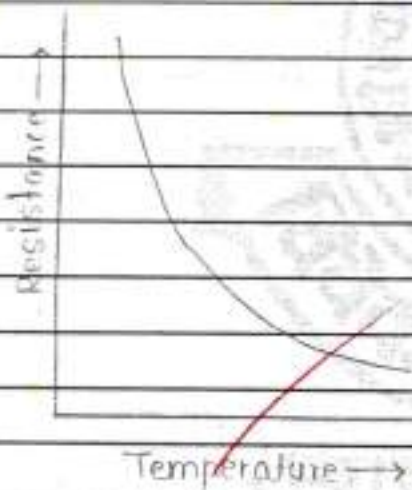
2 LVDT

Q.2

1 Thermistor -

Thermistor is a temp sensitive device IF the temp varies then the resistance of the thermistor either increases or decreases. By using this property, we can use it as a temperature sensor. In thermistors the semiconductor materials are used.

Thermistor are classified into two types are negative temperature coefficient Thermistor, Positive temp coefficient thermistor. In NTC thermistor the resistance decreases as the temperature increases, according to the following expression



$$R_T = R_0 \beta \left(\frac{1}{T} - \frac{1}{T_0} \right)$$

Features of Thermistor Thermometer -

- ① The typical size of a thermistor is 0.125 mm to 1.5 mm. The useful range of temperature that we can get in thermistor is 100°C to 300°C. Commercially available thermistors have nominal values of 1k, 2k,

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Bridge circuit formation using Thermistor -

When $R_T R_1 = R_2 R_3$, R_1, R_2, R_3 resistors are fixed value resistors then the output voltage can be varied due to change in resistance R_T .

$$V_{AB} = \frac{R_T}{R_T + R_3} * V_s \quad \& \quad V_{CD} = \frac{R_1}{R_1 + R_2} * V_s$$

→ 2 Construction and working of LVDT -

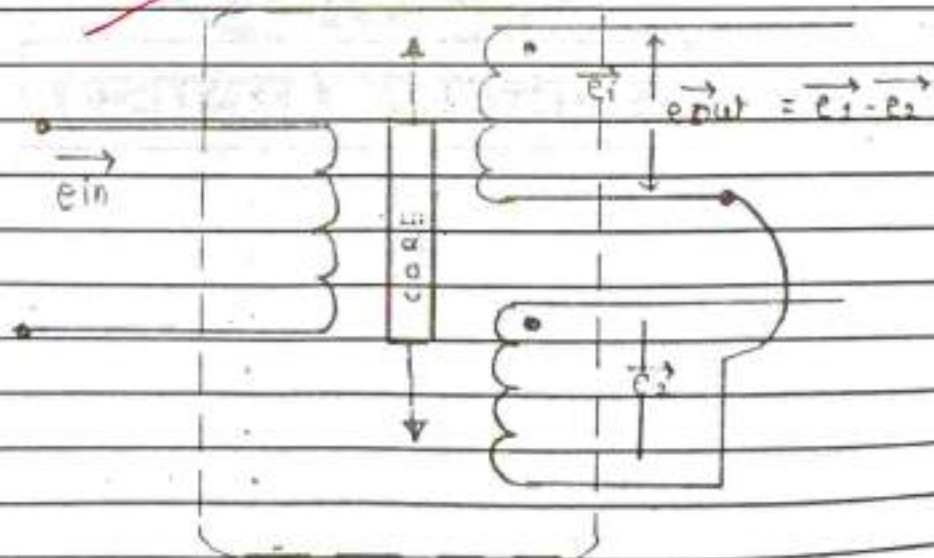
The term LVDT stands for the linear variable differential transformer. It is the most widely used inductive transducer that converts the linear motion into the electrical signals.

Construction of LVDT -

Main features of construction areas,

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- Both the secondary windings have equal no. of turns and are identically placed on the either side of primary winding.
- The primary winding is connected to an AC source which produces a flux in the air gap and voltages are induced in secondary winding.

Principle of Operation and working -



Working -

Case I - When the core is at null position when the core is at null position then the flux linking with both the secondary windings is equal, so the induced emf is equal in both the windings, so for no displacement the value of output emf as e_1 and e_2 both are equal

Case II - When the core is moved to upward of null position. In this case the flux linking with secondary winding S_1 is more as compared to flux linking with S_2

Case III - When the core is moved to downward of null position displacement to the downward of reference point) In this case magnitude of e_2 will be more as that of e_1

Vrushali Umesh Ropalkar

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Class : BSC III

Subject : Electronics

Test / Tutorial No. : Internal Exam

Div. :

Q.1

1. Ground wave propagation involve a radio signal that travels along the surface of the earth

2. The widely used shape for path antenna is Rectangular

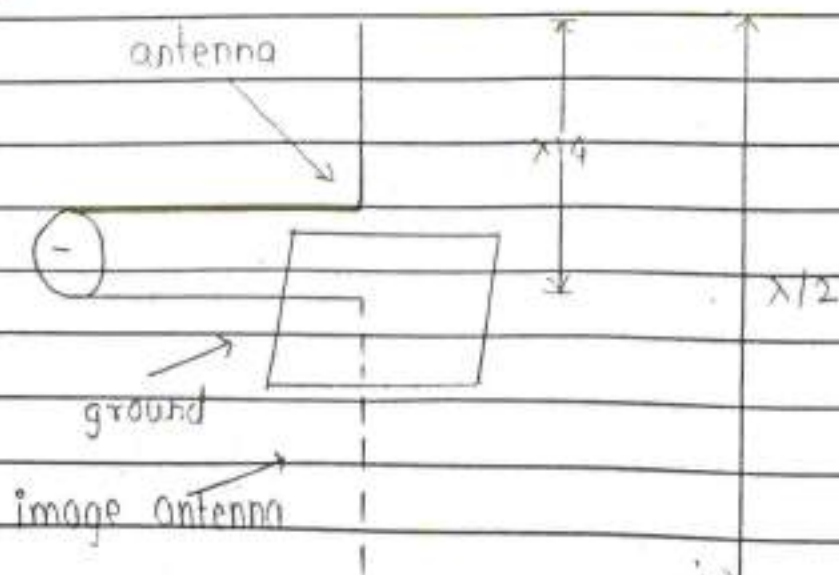
Q. 2

4. Define the following terms.

- a) Critical Frequency - It is highest frequency that returns to the ground after reflection from the ionosphere layer when transmitted vertical.
- b) maximum usable frequency - This is a limiting frequency at the specific angle of incidence other than the vertical which can be used for the sky wave propagation.
- L c) Skip distance - The skip distance is defined as the minimum distance from a transmit antenna that a sky wave at a given frequency will be returned to earth.
- d) Virtual height - When a wave refracted it is bent down gradually, but not sharply. However the path of incident wave and reflected wave are same if it is reflected from a surface located at a greater height of this layer. Such a greater height is termed as virtual height.

9 Monopole antenna - A monopole antenna is a class of radio antenna consisting of a straight rod-shaped conductor often mounted perpendicularly over some type of conductive surface called a ground plane. A monopole antenna is a half a dipole antenna placed on top of a ground plane as shown fig. The driving signal from a transmitter is applied, or for receiving antenna the output signal to receiver is taken between the lower end of the monopole and the ground plane. One side of the antenna feedline is attached to the lower end of the monopole often the earth. In constructs with a dipole antenna which consists of two identical rod conductors, with a signal from the transmitter applied between the two halves of the antenna.

Assuming the plane is infinite and perfectly conducting the monopole antenna will be equivalent to a dipole whose lower half is the image of the upper half. It is found that for a monopole antenna like a quarter wavelength vertical the ground acts as a plane to reflect the radio waves so that an image of the top half of the antenna is seen in the earth.



concept of monopole antenna.

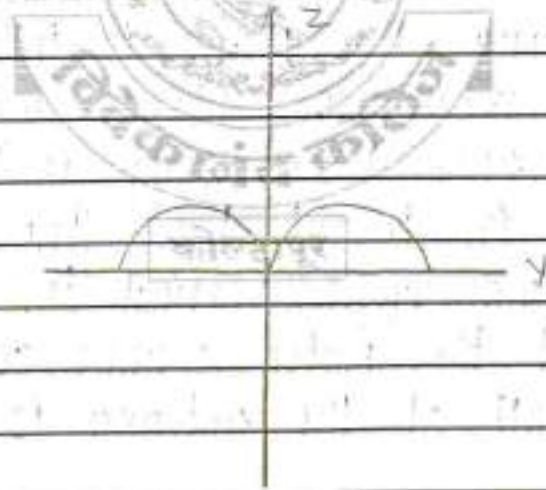
The current and charges on the monopole are the same as on the upper half of its dipole counterpart, but the terminal voltage is only half that of the dipole.

$$Z_{A, \text{mono}} = \frac{V_{A, \text{mono}}}{I_{A, \text{mono}}} = \frac{1/2 V_{A, \text{dipole}}}{1/2 I_{A, \text{dipole}}} = \frac{1}{2} Z_{A, \text{dipole}}$$

The directivity of a quarter wave monopole is twice, half of a half-wave dipole in free space.

$$D = 2(1.64) = 3.28 = 5.16 \text{ dB}$$

The radiation pattern for the monopole is shown in Fig



4

Ajay Mohan Suryavanshi

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
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$\frac{9}{10}$ 

Suppliment No. : 1

Roll No. : 8509

Class : BSc-III

Subject : Electronics

Test / Tutorial No. : Internal

Div. :

Q 1

i) Ground wave propagation involves a radio signal that travels along the surface of the earth.

ii) The widely used shape for patch antennas is Rectangular.

Q 2

4)

a) Critical Frequency :-

It is height frequency that returns to the ground after reflection from ionosphere layer when transmitted horizontally. After this frequency the ray will not bend towards the earth and no communication takes place.

b) Maximum Usable Frequency (MUF) :-

This is a limiting frequency at the specific angle of incidence ~~and~~ other than the vertical, which can be used for the sky wave propagation.

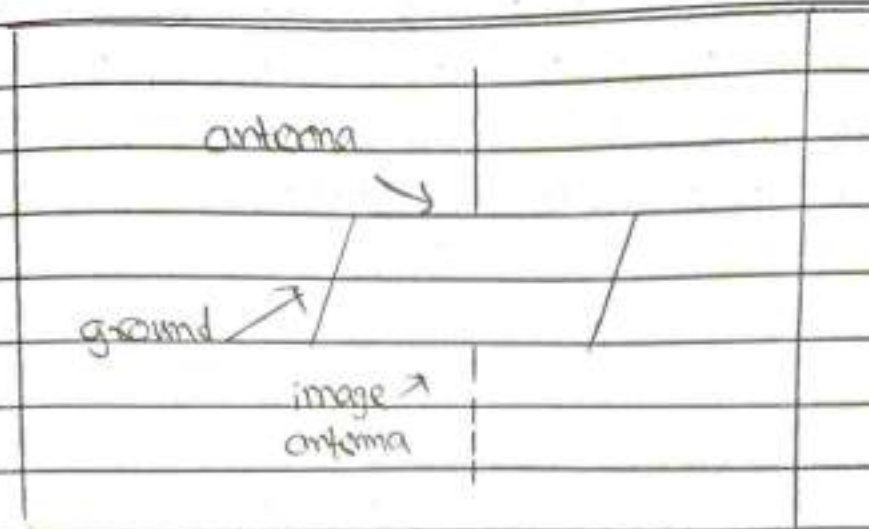
c) Skip Distance :-

The skip distance is the distance from the transmitter to the point where the sky wave first returns to the earth.

d) Virtual Height :-

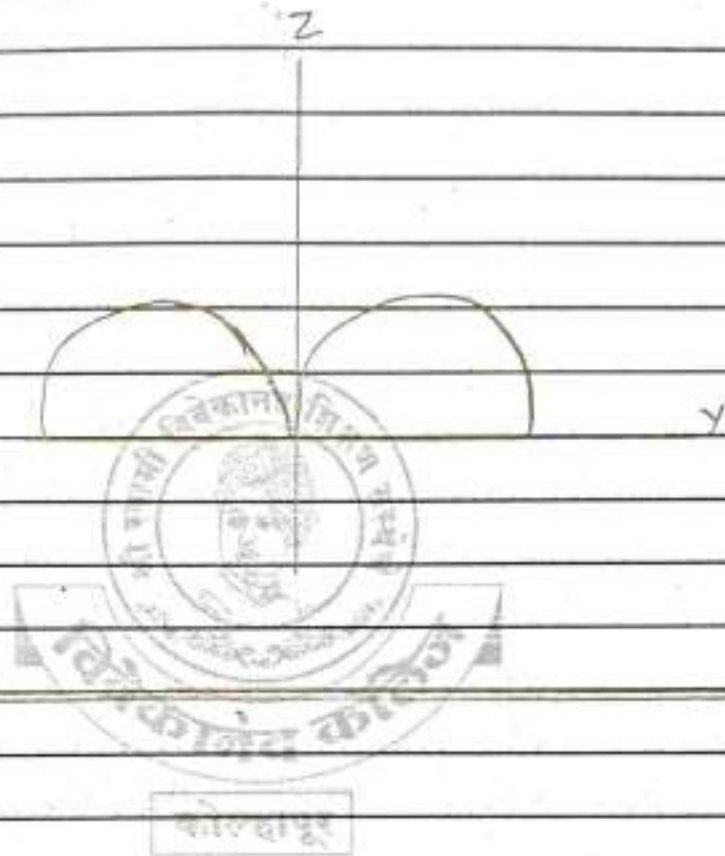
When a wave is refracted, it is bent down gradually but not sharply. However, the path of incident wave and reflected wave are same if it is reflected from a surface located at a greater height of this layer. Such greater height is called as virtual height.

2)



- i) Monopole antenna is class of the antenna consisting of straight and rod shaped conductor often mounted perpendicular over some type of conductive surface called a ground plate.
- ii) A monopole antenna is half of dipole placed on top of ground plate as diagram.
- iii) The driving signal from the transmitter is applied for receiving antenna output signal to the receiver is taken between lower end of monopole and the ground plane.
- iv) One side of the antenna feedline is attached to the lower end of the monopole and the other side is attached to the ground plane which is often the earth.
- v) This contrast with dipole antenna which consists of two identical rod conductors with the signal from the transmitter applied between the two halves of the antenna.
- vi) Assuming the planes is infinite and perfectly conducting the monopole antenna will be equivalent of the dipole antenna.

vii) It is found that a monopole antenna like as plane quarter wavelength vertical, the ground acts as plane reflect the radio waves so that an image of half antenna seen to be earth.



Name:- Nikhil Sunil Patil

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Suppliment No. : 1

Subject : Electronics

Roll No. : 8367

Test / Tutorial No. : Internal exam

Class : BSc III

Div. :

Q.1 i) Groundwave propagation involves a radio signal that travels along the surface of the earth

ii) The widely used shape for patch antennas is Rectangular

Q.2

4/

a)

Critical frequency :-

It is the highest frequency that turns to the ground after reflection from an ionosphere layer when transmitted ^{vertically} horizontally. After this frequency the ray can not bend towards earth.

Critical frequency is

$$f_c = \sqrt{81 N_{max}} = 9\sqrt{N_{max}}$$

b) Maximum usable frequency :- (MUF)

This is limiting frequency at the specific angle of incidence other than the vertical which can be used for the sky wave propagation

$$MUF = f_c / \cos i = f_c \sec i$$

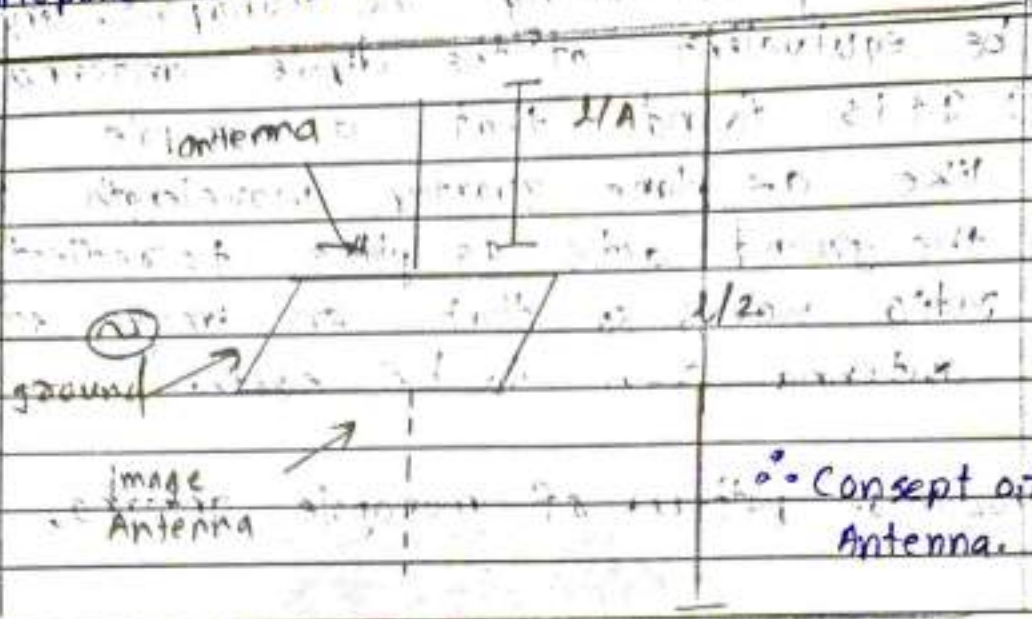
c) skip distance :-

skip distance It is defined as the maximum distance from the transmit antenna that a sky wave at a given frequency will be returned to earth.

d) Virtual Height :-

The maximum height that this hypothetical wave would have reached is the virtual height. wave is reflected bend down gradually but not sharply the path of incident wave and reflected wave same. Such greater height is called virtual height.

② Monopole antenna:-



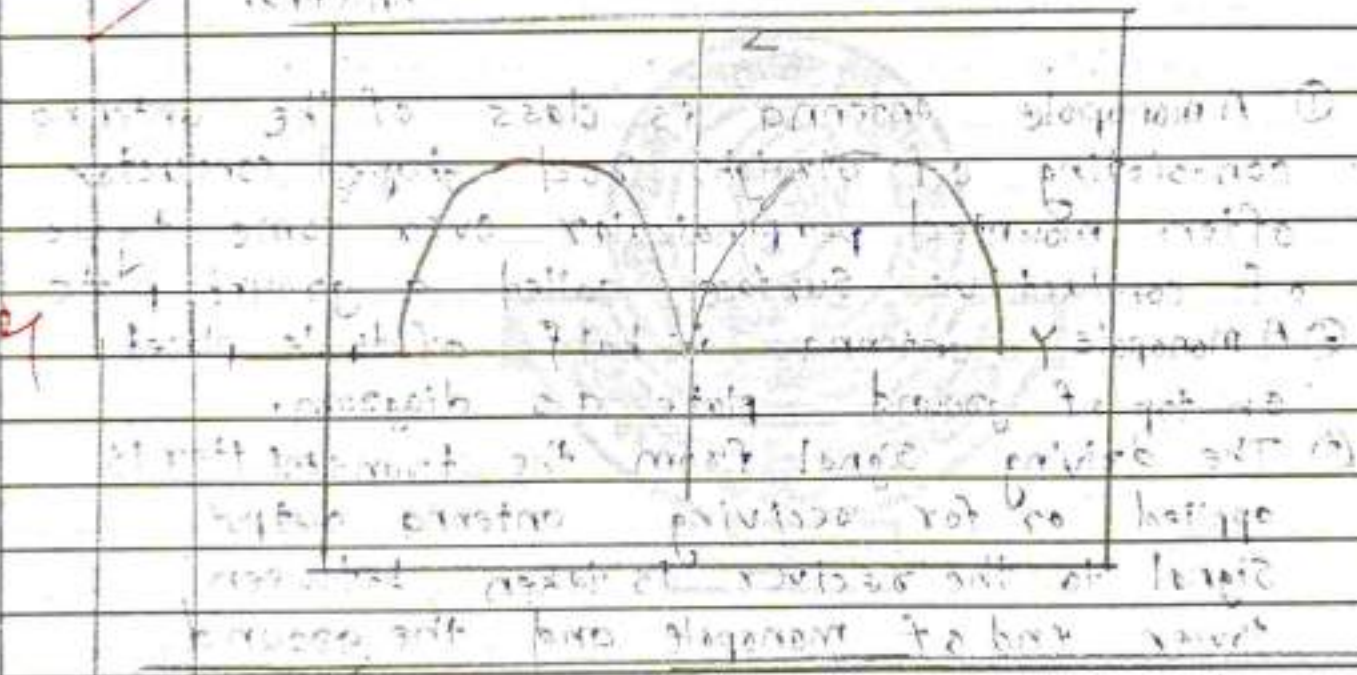
• Concept of Monopole Antenna.

- ① A monopole antenna is class of the antenna consisting of straight rod shaped conductor often mounted perpendicular over some type of conductive surface called a ground plate
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- ③ The driving signal from the transmitter is applied or for receiving antenna output signal to the receiver is taken between lower end of monopole and the ground plane.
- ④ One side of the antenna feedline is attached to the lower end of the monopole and the other side is attached to the ground plane which is often the earth.
- ⑤ This contrast with dipole antenna which consists of two identical rod conductors with the signal from the transmitter applied between the two terminals of the antenna.

⑥ Assuming the plane is infinite and perfectly conducting the monopole antenna will be equivalent of the dipole antenna.

⑦ It is found that a monopole antenna like a plane quarter wavelength vertical the ground acts as plane to reflect the radio waves so that an image of half antenna seen to be earth.

* Radiation pattern of monopole antenna.



⑧ The radiation pattern of the monopole antenna is similar to that of the dipole antenna. The radiation is maximum in the plane perpendicular to the antenna and minimum along the axis of the antenna. The radiation pattern is shown in the diagram above.

Name : Aniradha Vitthal Patil.

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3/10/20

Suppliment No. :

Subject : Electronics

Roll No. : 8366

Test / Tutorial No. : Internal Exam

Class : BSC EEE

Div. :

(Antennas wave propagation)

Q.17

i] Ground wave propagation involves a radio signal that travels along the surface of the earth

ii] The widely used shape for patch antennas is rectangular

Q2] 4] Define the following terms.

a] critical energy \rightarrow

It is the height frequency that turns to the ground after reflection from Ionosphere layer when transmitted ~~horizontally~~ ^{vertically}. After this frequency the ray can not bend towards earth. critical frequency (f_c) $\sqrt{f_c} = \sqrt{N_{max}}$

b] maximum usable frequency \rightarrow This is limiting frequency at the specific angle of incidence other than the vertical which can be used for the sky wave propagation.

$$MUF = f_c / \cos i = f_c \cdot \sec i$$

c] skip distance \rightarrow It is defined as the minimum distance from the transmit antenna that a sky wave of a given frequency will be returned to earth.

d] virtual height \rightarrow

The maximum height that the hypothetical wave would have reached is the virtual height.

Q 17

27

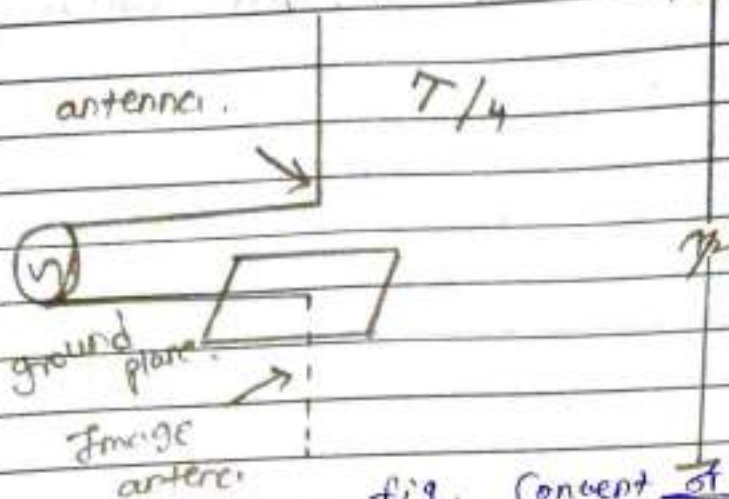


fig. Concept of monopole antenna.
1] The monopole antenna is class of the antenna consisting of straight rod shaped conductor, often mounted perpendicular over some type of conductive surface called a ground plane.

2] A monopole antenna is half of dipole placed on the top of the ground plane, as shown in fig.
3] The driving signal from the transmitter is applied or for receiving antenna output signal to the receiver is taken betⁿ lower end of monopole and the ground plane.

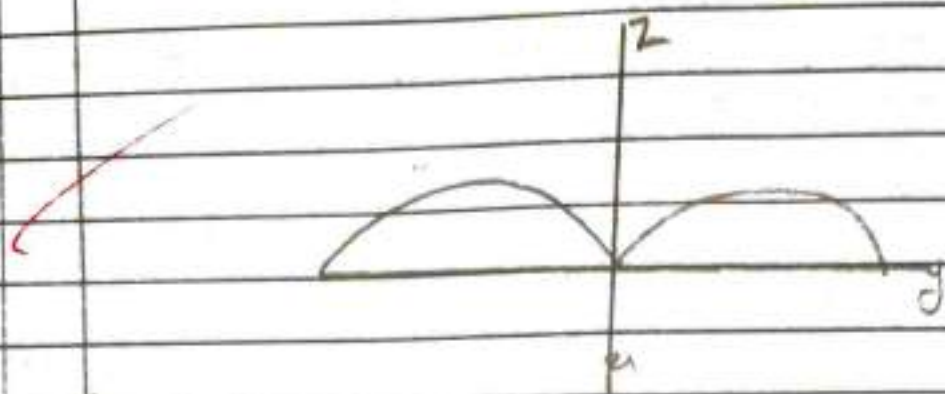
4] one side of the antenna feedline is attached to the lower end of the monopole and the other side is attached to the ground plane which is often the earth.

5] This contrast with dipole antenna which consists of two identical rod conductors with the signal from the transmitter applied betⁿ the two halves of the antenna.

6] Assuming the plane is infinite and perfectly conducting the monopole antenna will be equivalent to a dipole antenna.

7] It is found that for a monopole antenna like a quarter wavelength vertical the ground acts as plane of reflect the radio waves so that an image of half the antenna seen to be earth.

* Radiation pattern of monopole Antenna. $\frac{3}{2}$



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Subject : Electronics

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Div. :

2f2+3=7

Q.1

i)

→

c) Ground Wake

ii)

→

A) rectangular

2



Q.2

1.

→

micro. patch antenna called patch antenna to high performance aircraft satellite craft scale lite and missile application where size weight cost performance ease of installation of antenna may require microstrip patch antenna also very popular in the field of mobile communication patch antenna are usually used within the frequency range of 2-11 GHz.

✓

A microstrip antenna a generally consist of dielectric substance sandwiched between a radiating patch on the top and a ground plane on the other side as shown in fig the patch is made of conducting materials such as copper or gold and can take any possible shape.

2.

→ the frequency range wave propagation

4.4
a) critical frequency: (f_c)

it is the highest frequency that return to the ground after reflection from the ionosphere layer when transmitted vertically

$$f_c = \sqrt{81N_{max}} = 9\sqrt{N_{max}}$$

b) maximum usable frequency (MUF) :-

this is the limiting frequency at the specific angle of incidence other than the vertical which can be used for the sky wave propagation

$$MUF = \frac{f_c}{\cos \theta_i}$$

$$MUF = f_c \cdot \sec i$$

c) skip distance

the skip distance is the distance from the transmitter to the point where the sky wave propagation

Q.3

→

Ground wave propagation :-

micro wave frequency range is 30 MHz

